

GLT-25S2 Gearless Machine Instruction Manual (#1192)



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BULLETIN #1192 GLT-2582 GEARLESS TRACTION MACHINE

WARNING

This installation and service manual is intended for the use of qualified and authorized elevator personnel ONLY. For your safety and the safety of others, do not attempt ANY procedure that you are not qualified and authorized to perform. Recommended procedures must be done in accordance with the applicable rules of the latest edition of the National Electrical Code; the latest edition of ASME A17.1; and all governing local codes. Every attempt has been made to ensure that this guide is accurate and up to date. Hollister-Whitney Elevator Co. LLC assumes no liability for consequences resulting from any error or omission. Please notify Hollister-Whitney Elevator Co. LLC regarding any difficulties with this guide.

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Section

1 Introduction

1.1 Description

Thank you for choosing the Hollister Whitney Elevator Company (HWEC) GLT-25S2 Gearless Machine!

The GLT-25S2 machine has been designed for use in 2:1 roped, machine room and machine-room-less (MRL) applications with VVVF controls. The machine is designed with 30 poles to provide smooth, quiet, and long-lasting operation.

HWEC machines are designed to perform in a tolerant machine space. The machine space working temperature should be held between 35° F & 104° F, (1.7° C & 40° C) and humidity should be held to an average of 90% non-condensing.

1.2 Warranty Information

All parts and equipment manufactured by HWEC are guaranteed against defects in material and workmanship for a period of one (1) year from the date of shipment.

Warranty covers only the repair or replacement of parts, F.O.B. our factory, upon determination by inspection at our factory that warranty is applicable.

Equipment and components not of our manufacture are warranted only to the extent of the original manufacturer's warranty.

Our warranty specifically does not include any other incidental liability or expense such as transportation, labor, and unauthorized repairs.

Section

2 Safety Precautions

Read this section before any work is performed on elevator equipment.

* IMPORTANT -

The procedures contained in this manual are intended for the use of qualified elevator personnel. In the interest of your personal safety and the safety of others, do NOT attempt ANY procedure that you are NOT qualified to perform.

All procedures must be done in accordance with the applicable rules in the latest edition of the National Electrical Code; the latest edition of ASME A17.1; and any governing local codes.

2.1 Terms in This Manual

VCAUTION:

Caution statements identify conditions that could result in damage to the equipment or other property if improper procedures are followed!

♥WARNING:

Warning statements identify conditions that could result in personal injury if improper procedures are followed!

2.2 General Safety

Specific warnings and cautions are found where they apply, and DO NOT appear in this summary.

2.3 Electrical Safety

All wiring must be in accordance with the National Electrical Code and must be consistent with all state and local codes.

2.4 Electrical Hazards

Electric shocks can cause personal injury or loss of life. Circuit breakers, switches and fuses may NOT disconnect all power to the equipment. Always refer to the wiring diagrams. Whether the A/C supply is grounded or not, high voltage will be present at many points.

2.5 Mainline Disconnect

Unless otherwise suggested, always turn OFF. Lock and tag out the mainline disconnect to remove power from the equipment.

2.6 Test Equipment Safety

Always refer to manufactures' instruction book for proper test equipment operation and adjustments.

Megger testing, or buzzer type continuity testers, can damage electronic components. Connection of devices such as voltmeters on certain low-level analog circuits may degrade electronic system performance. Always use a voltmeter with a minimum impedance of 1M Ohm/Volt. A digital voltmeter is recommended.

2.7 When Power Is On

Dangerous voltages exist at several points in some products. To avoid personal injury, do NOT touch exposed electrical connections or components while power is On.

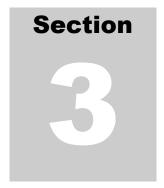
2.8 Product Specific Warnings



GLT-25S2 machine MUST be balanced during hoisting. See paragraph 3.4 for proper lifting configurations.

WARNING

Hang the elevator car before removing ANY bolts. Failure to do so may result in severe injury and equipment damage.



3 Arrival of the Equipment

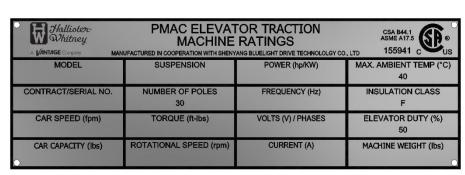
3.1 Receiving

Immediately upon arrival of the machine, make a visual check for any external damage. If any damage incurred in transit is found, make notice of the claim in the presence of the carrier, and notify HWEC. If necessary, do not put these machines into operation without first consulting HWEC.

If the machine has gotten wet during transportation, make notice of the claim in the presence of the carrier and notify HWEC. See also Section 3.6.

3.2 Data Tag

Check the machine data tag to ensure the machine conforms to your order.



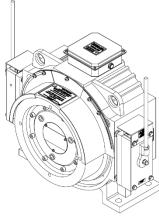


Figure 1

3.3 Handling

The machine will be delivered on a wooden pallet. It can be left on the pallet and moved with a standard fork truck or pallet jack.

3.4 Hoisting

The machine weighs about 850 pounds (385 kg). When removing the machine from the pallet, it must be lifted using the lifting holes provided at the top of the machine.

When lifting the machine, use a spreader beam or other suitable rigging device to pull straight up on the lifting holes.

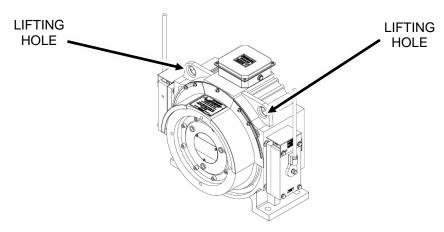


Figure 2

9 WARNING

Use only the lifting holes when lifting the machine! Do not use any other machine component to lift the machine! Lifting the machine by any other component will result in damage to the machine or possible failure of the component resulting in the machine falling from the hoisting system!

Follow all the necessary precautions to avoid damage to the machine or risk to personnel when moving or hoisting the machine.

3.5 Storage

During storage in a warehouse or on the elevator job site, precautions must be taken to protect the machine from dust, dirt, moisture, metal shavings and temperature extremes.

For short term storage, place the machine in a warm, dry and clean environment.

Protect the machine from harsh weather conditions and temperature variations that can lead to condensation.

Protect from dust and metal shavings. Metal dust and shavings can be attracted into the machine by the magnets.

For longer term storage, follow the recommendations above plus; place the machine in a sealed, waterproof enclosure. Add a dehydrating packet that is sized for the enclosure's volume and humidity level.

3.6 Moisture, Condensation

Before installing the machine, and before any voltage is applied, check the machine for condensation, or any evidence of moisture or water. If any evidence of wetness is found, contact HWEC for drying instructions.

After the machine has been dried per factory instructions, it will be necessary to verify the insulation between each coil phase and earth ground. Using an insulation tester (or megohmmeter) check the insulation resistance at 500VDC. The resistance should be NO LESS than 100 Mohm.

Section



4 Application

4.1 Overview

The GLT-25S2 machine is synchronous permanent magnet gearless machine designed for elevators. The machine has 30 poles to provide smooth, quiet, and long-lasting operation. Its configuration allows elevator capacity up to 2500 lbs. with 2:1 roping, single wrap arrangement at 50% counterbalance with up to a 9000 lb. shaft load. See Section 4.4 for complete specifications. The overall system load is calculated by adding the following items:

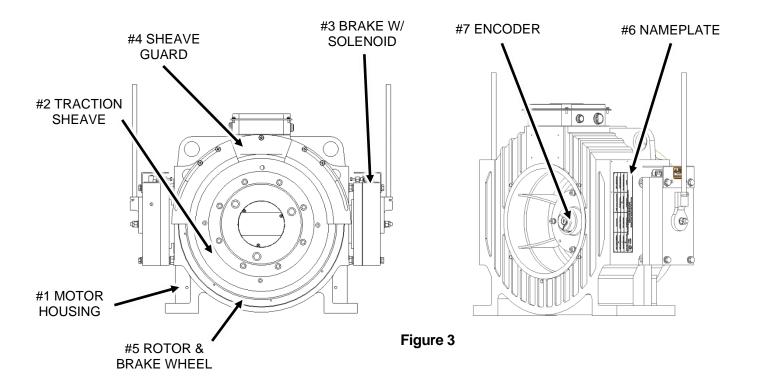
Empty Car Weight + Counterbalance Weight + Capacity + Hoist Rope Weight + Compensation Weight + Traveling Cable Weight

The GLT-25S2 machine brake system is equipped with two block brakes.

The latest HWEC manuals, bulletins and procedures are available for download from the HWEC website.

The following is a list of major components of the GLT-25S2 machines. Along with a description of their functions, there is an overview of some of the critical adjustments and maintenance information. See Installation and Maintenance for detail.

- 1. **PM Motor Housing** The housing contains the PM windings used to provide the necessary torque and speed to move the elevator in operation.
- 2. **Traction Sheave** A grooved sheave is connected directly to the machine rotor. The grooves provide traction between the sheave and the hoist ropes.
- 3. **Brake** The electromechanical device is used to prevent the elevator from moving when the car is at rest.
- 4. **Sheave Guard/Rope Retainer** Provides rope retention and keeps hoist ropes away from contact after rope installation.
- 5. **Machine Rotor & Brake Wheel** The brake wheel is connected to the main shaft. When the brake is energized, the brake is released from the brake wheel.
- 6. **Nameplate** Displays the machine rated data and manual factory contact/serial number information.
- 7. **Encoder** (Behind Cover) This device is directly coupled to the rotor of the machine. It is provided to give the absolute speed feedback of the hoist motor to the inverter drive system and to the elevator controller.



4.2 Codes and Standards

These machines are designed to comply with ASME A17.1/CSA B44 code. The motors are designed with insulation class F minimum and have been approved by and carry a CSA approved label.

4.3 Environmental Specifications

- Operating ambient temperature: 35° F to 104° F (1.7 C to 40 C)
- Humidity average of 90% non-condensing

4.4 Machine Specifications

- Traction Sheave (removeable) Diameter: 15.75 in.
- Main and emergency block brakes. Each capable of holding 125% of the load.
- Brake switches, wired normally close standard.
- Heidenhain ECN1313 2048 encoder and 1.5-meter-long cable (standard).
- Sheave guard/rope retainer.
- Machine dimensions and parts list can be found at the end of this book.

CWT (%)																											
00	90			90			20			90			20			20			50			20			20		
MAX ACCEL TORQUE (ft-lbs)	812		812		812			982			982			982			1130			1130			1130				
RATED TORQUE (ft-lbs)	406		406		406			491			491			491			565			565			565				
PEAK CURRENT (A)	28.3		48.2		72.5		34.3		58.1			87.6			39.4			67.0		100.8							
CURRENT (A)	11.8			20.1		30.2		14.3		24.2		36.5			16.4		27.9		42.0								
RATED FREQ (Hz)	12.2	18.3	24.3	30.0	36.0	42.5	48.6	54.7	60.7	12.2	18.3	24.3	30.0	36.0	42.5	48.6	54.7	60.7	12.2	18.3	24.3	30.0	36.0	42.5	48.6	54.7	2.09
ACTUAL VOLTAGE	159	238	317	220	564	308	234	263	262	163	244	325	224	569	314	237	266	596	170	255	340	228	273	319	242	273	303
RATED VOLTAGE		380			380			380			380			380			380			380			380			380	
RATED (rpm)	48.5	72.7	6.96	121.2	145.4	169.7	193.9	218.1	242.4	48.5	72.7	96.9	121.2	145.4	169.7	193.9	218.1	242.4	48.5	72.7	6.96	121.2	145.4	169.7	193.9	218.1	242.4
POLES		30			30			30			30			30			30			30			30			30	
MOTOR RATING (kW)	2.8	4.2	5.6	7.0	8.4	9.8	11.2	12.6	14.0	3.4	5.1	6.8	8.4	10.1	11.8	13.5	15.2	16.9	3.9	5.8	7.8	9.7	11.7	13.6	15.6	17.5	19.4
MOTOR RATING (HP)	3.7	9.9	7.5	9.4	11.2	13.1	15.0	16.9	18.7	4.5	8.9	9.1	11.3	13.6	15.9	18.1	20.4	22.7	5.2	7.8	10.4	13.0	15.6	18.3	20.9	23.5	26.1
CAPACITY (lbs)		1760			1760			1760			2200			2200			2200			2500			2500			2500	
SPEED (fpm)	100	150	200	250	300	350	400	450	200	100	150	200	250	300	350	400	450	200	100	150	200	250	300	350	400	450	200
0																											
HOLLISTER- WHITNEY ORDERING PART #		GLT-25S2-C-T401			GLT-25S2-C-T401			GLT-25S2-C-T401			GLT-25S2-C-T402			GLT-25S2-C-T402			GLT-25S2-C-T402			GLT-25S2-C-T403			GLT-25S2-C-T403			GLT-25S2-C-T403	
	SPEED CAPACITY MOTOR MOTOR (fpm) (lbs) (HP) (kW) (HP) (kW)	SPEED CAPACITY MOTOR MOTOR RATED R	SPEED CAPACITY MOTOR RATING R	C C C C C C C C C C	C CAPACITY MOTOR MOTOR RATED RATED	C CAPACITY MOTOR MOTOR	Capacity Motor M	SPEED CAPACITY MOTOR M	C CAPACITY MOTOR MOTOR	C CAPACITY MOTOR MOTOR	C CAPACITY MOTOR MOTOR	Column C	C CAPACITY MOTOR MOTOR	Capacity Capacity Motor Capacity Motor Capacity Motor Capacity Motor Capacity Motor Capacity Ca	C CAPACITY MOTOR MOTOR	C) SPEED CAPACITY MOTOR (Hb) MOTOR (HP) POLES (rpm) RATED (rpm) RATED (HD) RATED (HD)	Column C	SPEED CAPACITY MOTOR MOTOR MOTOR (fpm) MOTOR (C) SPEED CAPACITY MOTOR MOTOR POLES PATED RATED RATED RATED RATED RATED RATED RATED RATED RATED CURRENT CURRENT CURRENT TORQUE 100 100 3.7 2.8 48.5 30 12.2 (Hz) (A) (A) (A) (A) (Hz) (Hz) 250 150 4.2 3.0 72.7 380 284 11.8 28.3 406 250 1760 11.2 8.4 3.0 121.2 20 30.1 48.5 30.0 20.1 48.2 406 360 1760 11.2 8.4 3.0 145.4 380 264 36.0 20.1 48.2 406 400 1760 11.2 8.4 30 145.4 380 284 48.6 48.6 48.6 48.6 48.6 48.6 48.6 48.6 48.6 48.6 48.6 <	CD (fpm) CAPACITY MOTOR (WM) MOTOR (WM) MOTOR (WM) MOTOR (WM) POLES (FPM) RATED (PPM) RATED (PPM) RATED (PPM) RATED (PPM) RATING (PPM) RATING (PPM)	SPEED CAPACITY MOTOR MOTOR POLES FRATED RATED ACTUARE FREQ CURRENT CURRENT CURRENT TORQUE 100 (1bs) (1hs) (1hs)	(fpm) MOTOR (fpm) MOTOR (fpm) MOTOR (fpm) POLES (fpm) RATED (fpm) RATED ACITAGE (fpm) ACITAGE (fpm) ACITAGE (fpm)	SPEED CAPACITY MOTOR MOTOR POLES FRATED RATED RATED	Column C	Column C	Column Column Motor Mo	Column Part Part

Table 1 – Maximum Detailed Specifications

4.5 Brake Specifications

- Two brakes are supplied standard from the factory. One brake is meant to serve as a
 primary machine brake and the other as a secondary emergency brake. Please contact
 Hollister-Whitney for details regarding using a Rope Gripper® as the emergency brake
 with a GLT-25S2 machine.
- Brake switch rating DC 110 V Rated current 1.57 A.
- The opening voltage of the brake is not more than 110 V, the releasing voltage is not more than 70 V, and the control range is 15 V-30 V.

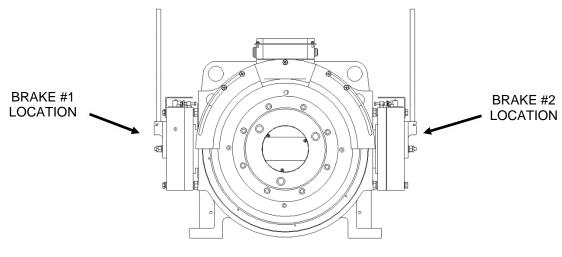


Figure 4



5 Installation

5.1 Machine Mounting

Before hoisting the machine into place, verify all the hoisting equipment is rated for the 850 pounds (385 kg) weight of the machine. See Section 3.4.

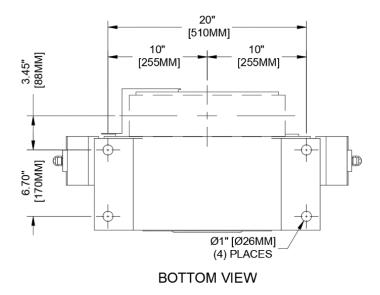
Provide a level, structurally supported (rated for the load on the machine) machine space with proper clearance around the machine for maintenance and adjustments.

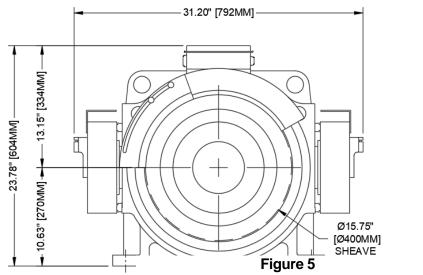
This machine is primarily intended to be mounted in traditional overhead applications with down-pull forces on the traction sheave.

5.1.1 Traditional Overhead Mounting

Anchor the machine to the structural support surface using the (4) mounting hole locations in the base. The hardware required to anchor the machine to the support surface should be at least 7/8" diameter, grade #5 minimum, with standard washers. Hardware adhering to ASME A325 is also suitable.

Note - No mounting hardware is shipped with the machine due to the varying mounting surface thicknesses.





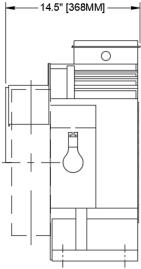


Figure 6

5.2 Electrical Connection

Use the project wiring diagrams (with the motor configuration information) to connect the motor to the controller.

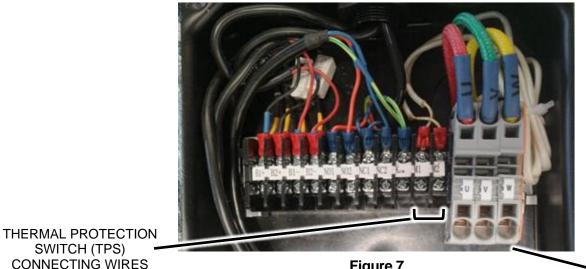
WARNING

Before performing any electrical connections, make sure that power supply is turned off. Only then proceed with connecting electrical leads to power supply. Never work in machine electrical enclosure while power supply is on!

Direct connection to the three-phase power is forbidden, it may destroy the motor.

5.2.1 Machine Wiring

- The Thermal Protection Switch (TPS) is wired with leads labeled and supplied into the machine electrical enclosure. Refer to Figure 6.
- Consult your controller manufacturer for appropriate TPS connections.
- Verify the electrical supply from the elevator drive and brake power supplies match the machine data tag. Refer to Figure 1.



SWITCH (TPS)

Figure 7

CONNECT CONTROLLER **WIRES**

- Connect the U-V-W lines from the drive as shown.
- Earth Ground connects to the ground lug terminal inside the electrical enclosure.

Note - Check and tighten all leads (motor side and line side) on installation.

9 WARNING

The machine and emergency brake coils must be independent!

It is the responsibility of the user to connect the motor in accordance with the current legislation and regulations in the country of use. This is particularly important in regard to wire sizes used to connect the power and earth ground and the type and size of fuses.

5.2.2 Brake Wiring

- Connect the machine brake and emergency brake as shown.
- The brake switches are wired normally closed from HWEC.
- To change the switches to function as normally closed, remove the blue wire from the terminal block in the electrical enclosure, and replace it with the spare gray wire coming from the brake switch.

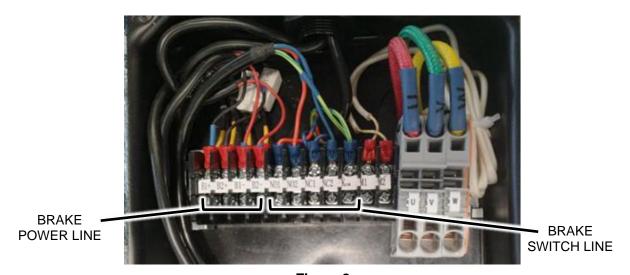


Figure 8

WARNING

- Brake coils are designed to be de-energized during each elevator stop.
- Verify brake voltage with a meter at the machine.
- 110 VDC excitation voltage for 3 seconds.
- 70 VDC "hold" voltage.

5.3 Brake Adjustment

9 WARNING

Before performing any maintenance on the machine brakes, take all necessary safety precautions to immobilize the car and counterweight to prevent any unintended movement during the maintenance period that may result in injury or death!

9 WARNING

Brakes must be adjusted after the car and counterweight are suspended by the machine!

As brake pads are worn or new pads are installed readjustment is required.

Read all of section 5.3 prior to adjusting brake!

5.3.1 Required Tools

- TORQUE WRENCH (45 FT-LBS)
- 16MM SOCKET
- 21MM OPEN END WRENCH
- 0.012" (0.30MM) FEELER GUAGE (USED AS GO)
- 0.016" (0.40MM) FEELER GUAGE (USED AS NO-GO)
- 0.022" (0.55MM) FEELER GUAGE (MAX AIR GAP CHECK)

5.3.2 Air gap (See Figure 9 through Figure 12)

The air gap of the brake is the space between the brake body and the moveable shoe plate (shown in Figure 9). This gap must be checked to ensure proper operation of the brake. The correct air gap is between 0.012" (0.30 mm) to 0.022" (0.55 mm). It is preferable to keep the gap close to minimum < 0.016" (0.36 mm).



Figure 9



Figure 10

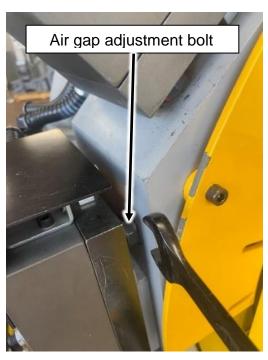


Figure 11

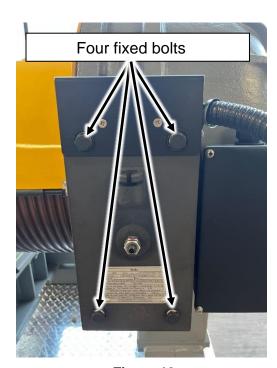


Figure 12

5.3.2.1 Air gap adjustment

An initial air gap check is to take place after the block brake has been properly installed and fixed bolts torqued to 45 ft-lb. (car and counterweight suspended by machine).

- 1. Using a 16 mm wrench, loosen the four fixed bolts. See Figure 10.
- 2. Using a torque wrench and 16 mm socket, torque the fixed bolts in an "X" pattern to 45 ft-lb (60 N-m) See Figure 10.
- 3. Confirm the air gap using a 0.012" (0.30 mm) and 0.016" (0.36 mm) go no-go feeler gauge to check the air gap at all four corners. The 0.012 (0.030 mm) go should feeler gauge should fit and the 0.016" (0.36 mm) should not fit. If this is the case, no adjustment is necessary. See Figure 9.

5.3.2.2 When the air gap of brake is more than 0.016" (0.36 mm), please do as follows:

- 1. Loosen one of the 4 fixed bolts with a 16 mm wrench. See Figure 10.
- 2. Use a 21 mm wrench, rotate the adjustment bolt corresponding to the loosened fixed bolt in small increments, less than ½ a flat of the hex head, counterclockwise. See Figure 11.
- 3. Retorque the 16mm fixed bolts to 45 ft-lbs. (60 N-m) See Figure 10.
- 4. Confirm air gap is 0.012 (0.30mm) to 0.016" (0.36 mm) using a feeler gauge. See Figure 9. Repeat for 3 remaining bolts.

5.3.2.3 When the air gap of brake is less than 0.012" (0.30 mm) please do as follows:

- 1. Loosen one fixed bolt with a 16 mm wrench see Figure 10.
- 2. Turn the 21 mm adjustment bolt corresponding to the loosened fixed bolt clockwise in small increments, less than ½ turn of the hex head flat. See Figure 11.
- 3. Retorque 16 mm fixed bolts to 45 ft-lb (60 N-m). See Figure 10.
- 4. Confirm air gap is within 0.012" (0.30 mm) to 0.016" (0.36 mm) using a feeler gauge. See Figure 9.

5.3.3 Manual Brake Release "Arm Free play"

- Check "free travel" only after 5.3.1 Brake Air Gap has been completed.
- Manual release arm "free travel is factory set to ½" both directions. See Figure 13.
- Move Brake Arm without handle as shown below, while measuring the travel.
- If Adjustment is needed contact HOLLISTER WHITNEY ELEVATOR.



Figure 13

5.3.4 Verify Brake Function

When testing the brakes electrically energize them. Once brakes are adjusted run the car to verify the brakes are relatively quiet on stop and start. Verify no noticeable rubbing noise occurs during machine operation. Once adjustment is confirmed ensure dust guards are present to prevent dust buildup which can cause brake failure.

5.4 Brake Burnishing



Brakes must be burnished to achieve full stopping torque!

Each brake on the machine must be burnished separately. Repeat the following procedure for each brake.

- 1. Clamp the brake on the rotor. Ensure brake circuit is de-energized.
- 2. Run the elevator in the direction of the load at 11 RPM for 1 minute.
 - a. If the overall travel of the elevator will not allow the burnishing time to be met in one pass, open (energize) the brake at the bottom of the hoist way, lift the load back to the top, and repeat the run until the burnishing time is achieved.
 - b. Stop the elevator occasionally to ensure the brake and motor do not overheat.
- 3. After burnishing time is achieved re-verify the air gap between the brake pads and rotor.
- 4. Ensure air gap is within 0.012" (0.30 mm) to 0.016" (0.36 mm) using a feeler gauge.

5.5 Encoder Connection

The machines are supplied with Heidenhain ECN1313 2048 encoder. A 1.5-meter encoder cable is connected to the encoder and extends from the back of the machine.

Connect the supplied encoder cable to the encoder cable extending from the back of the machine.

When using a KEB drive, the encoder cable can be used "as-is."

When using any other manufacturer's drive, consult control manufacturer for cable compatibility and availability. DO NOT modify the KEB cable without first consulting the control manufacturer. Any modification of the KEB cable voids its warranty.

5.6 Startup

Verify all the motor related settings in the elevator controller match the information on the machine data tag. Refer to Figure 1.

Verify that all the brake parameters match the information on the machine data tag. Refer to Figure 1.

Follow the controller manufacturer's procedure for alignment of the magnets (motor learn).

Briefly run the machine to verify the machine functionality and brake operation.

Verify the drive sheave is plumb and aligned with the rope drop locations.

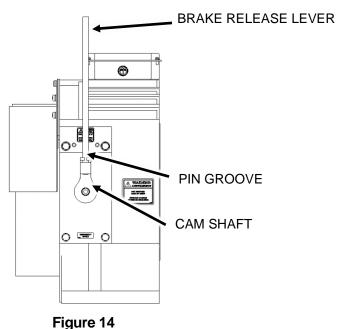
Install the hoist ropes, adjust the rope shackles, and check the ropes for equal tension. The rope tension must be uniform, or it may cause vibration and premature wear on the traction sheave and hoist ropes.

Re-verify the traction sheave plumb once the machine is fully loaded.

Manual Brake Release

The brakes can be manually released in the event of loss of power.

NOTE: The manual releasing device should be operated by 2 professionals, and make sure the power is shut down first.



- 1. Insert the brake release lever into the cam release on top of each brake. Align the pin on the brake release lever with the mating groove on the cam release to prevent the brake release lever from slipping.
- 2. Apply force to the end of the brake release lever until the brake releases from the brake wheel.
- 3. The brake release levers must be removed from the cam release prior to normal elevator operation.

Section

6 Maintenance



Before performing any maintenance checks on equipment, take all the necessary safety precautions to immobilize the car and counterweight to prevent any unintended movement during the maintenance period that may result in injury or death!

6.1 General

To keep equipment functioning efficiently, good maintenance practices must be established, observed, and maintained. Systematic inspections of the equipment should be scheduled, and records kept of these inspections. Monitoring these records will indicate any sign of a potential issue.

Each installation has its own special conditions, so it is not possible for HWEC to outline an overall plan for periodic maintenance. HWEC would recommend, at a minimum, yearly inspections, but installation conditions may warrant a more frequent schedule. The maintenance contractor will need to make the final determination.

6.2 Cleaning

Dirt, dust, excess lubrication, and moisture are the greatest enemies of electrical equipment and of maintenance teams in general. Dirt and dust layers on a machine can prevent heat dissipation, which can lead to overheating and eventual insulation breakdown. Many types of dust in an elevator machine room are electrically conductive and can also lead to insulation failure. Dust and dirt can draw moisture to unpainted surfaces such as brake rods causing oxidation that can cause brake faults. Excess lubrication can draw dust and dirt as well.

Dust and dirt can be removed from surfaces with a dry, lint-free cloth, or with suction. With suction, however, care must be taken to not build up or discharge static electricity while cleaning. Dry, compressed air (at less than 50psi) may also be used to remove dirt and dust, however, this must be closely monitored as the compressed air will re-suspend the dust and dirt in the machine room atmosphere.

6.3 Bearings

Bearings have been sized for the maximum speeds, loads and capacities found in this manual at 50% duty. The GLT-25S2 machine uses sealed bearings, no need to maintain, no need to add grease. When it is damaged, replace it with the same type.

Bearings L₁₀ calculated life rating (based on speed, loads and 50% duty) is approximately 20 years. Please note that installation conditions vary, so shorter or longer bearing life may be experienced.

6.4 Brake Wear



If the brake pad wears too much, the brake will be disabled.

6.4.1 Suggested check cycle

- Every 3 months after installation in the first 6 months.
- Every 1 year afterwards.

6.4.2 Benchmark Criteria

- Check the brake for flexibility, the brake pad and traction sheave for wear, and the bearings. Replace worn and damaged parts when necessary.
- As the brake pad wears it adds to the air gap and could contribute to braking noise. You may adjust the air gap as detailed in Section 0.
- If brake pad wear is excessive replace the brake pad or replace the entire brake assembly. See Figure 15.

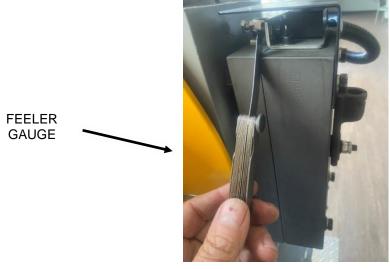


Figure 15

6.5 Other Items

The traction wheel, brake shoe, and brake wheel are usually the only components that will wear. Among them, the brake wheel is most unlikely to wear. Brake pads are more likely to wear but can be monitored with feeler gauges. Refer to the brake section of this manual for brake inspection procedures.

The winding working temperature of traction machine shall not exceed 130 °C. It can be controlled by the thermal switch in the main machine. When the temperature reaches 130 °C, the traction machine shall be stopped.

When the traction machine rotates under the passive condition, it will be in the state of power generation. At this time, high voltage will be generated at the host terminal. Attention shall be paid to avoid electric shock and equipment damage.

Grease and other impurities shall be avoided between the brake pad and the brake wheel to avoid the decrease of braking force of the brake system. If the residual thickness of the brake pad is less than 5 mm due to wear, the brake pad shall be replaced.

Traction wheels are the most likely item on the machines to wear. Periodic measurements of rope depth and the evenness of wear for all ropes (groove depth should wear evenly) should be monitored. Cable should not be more than 0.125 inch (1/8") below the outer rim of the traction wheel. If cable(s), are below 0.125 inch, or if wear is uneven, replace the traction wheel and cables.

Check machine guarding and rope retainers for clearance and attachment hardware for tightness. Adjust as necessary.

Section

7 Replacement

9 WARNING

Have only qualified personnel perform the replacement work. The person who performs the replacement work must make sure that the machine power is off and that the elevator will not move unexpectedly.

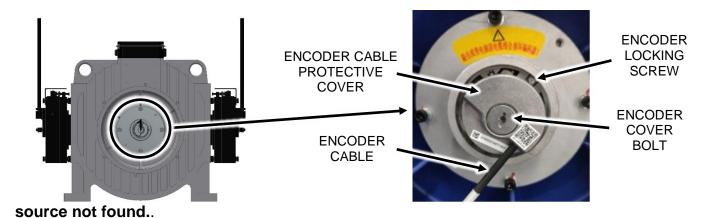
7.1 Encoder Replacement

Required Tools & Materials:

- Encoder (Heidenhain ECN1313 2048)
- Hex wrench
 - o 2 mm
 - o 4 mm
 - o 6 mm
 - o 8 mm
- Hex sockets
 - o 2 mm
 - o 4 mm
- Torque Wrench (Need to measure 9 in-lbs. and 44 in-lbs.)
- M10 bolt (at least 1" or 25 mm in length)

7.1.1 Encoder Removal

The encoder can be removed from the back of the machine. See Figure 16Error! Reference



1. Remove the encoder cover bolt and the encoder cable protective cover using the hex wrench (4 mm). See Figure 17Error! Reference source not found.







Figure 18

2. Carefully remove encoder cable, See Figure 18. **Note: Do not apply excessive pressure on the cable. It may destroy the encoder cable.**







Figure 17

3. Find the encoder locking screw and loosen the encoder locking screw M2.5. The screw does not need to be removed. See Figure 19Error! Reference source not found.



Figure 19

4. Loosen the bolt M5 inside by hex wrench (4 mm) 2~3 turns only. Do not remove this bolt yet (M5 bolt must remain in the encoder so the M10 bolt can push against it). See Figure 20.



Figure 20

5. Insert an M10 bolt into the encoder housing. See Figure 21.





Figure 21

6. Turn the M10 bolt against the M5x50 bolt to push the encoder from the shaft. The encoder will "pop" free and will be loose to the touch yet still retained by the M5 bolt. See Figure 22Figure .



Figure 22

7. Remove both bolts and the encoder. See Figure 23.



Figure 23

7.1.2 Encoder Installation

What's in the box, see Figure 24Figure.



Figure 24

1. Loosen and remove the bolt M2.5 and nut assembly in the new encoder. See Figure 25Figure .





Figure 25

2. There is a taper in the front of the encoder shaft, put the encoder shaft into the hole of the shaft. See Figure 26.

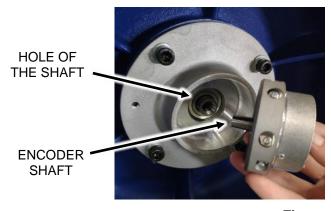




Figure 26

3. Install the encoder. Use the bolt M5 to secure the encoder to the encoder cover by hex wrench (4mm). Use 4mm socket Allen and torque wrench to tighten the bolt to 44 in-lbs. See Figure 27Figure.





Figure 27

4. Rotate the encoder, it should be very flexible at this time, tighten the encoder locking screw according to 11 in-lbs. by a hex wrench so the encoder outer cannot rotate by hand. See Figure 28Figure.



Figure 28

5. Install the encoder cable on the encoder. Take care to orient the plug and socket correctly. See Figure 29Figure .





Figure 29

6. Place the cable cover on the encoder and secure with the encoder cover bolt (and cover) to the encoder. See Figure 30.







Figure 30

- 7. Reconnect the power supply of machine and test it.
- 8. Align the encoder per controller instructions.

7.2 Brake Replacement

Required Tools & Materials:

- Adjustable wrench
- Hex wrench (4 mm, 5 mm)
- Small flat head screwdriver

9 WARNING

Before performing any maintenance on the machine brake(s), land the counterweight and take all the necessary safety precautions to immobilize the car and counterweight to prevent any unintended movement during the maintenance period that may result in injury or death!

Read the entire brake replacement procedure before beginning any of the steps outlined below. Contact HWEC with any questions prior to beginning the brake repair or replacement.

Before opening any electrical enclosures on the machine, remove all electricity from the machine and brakes to prevent electrical shock that may result in injury or death during the maintenance period!

7.2.1 Brake Removal

- 1. Remove covers as necessary to access terminal blocks and brake pin set screw (4 mm hex key).
- 2. Disconnect machine power, see Figure 31.

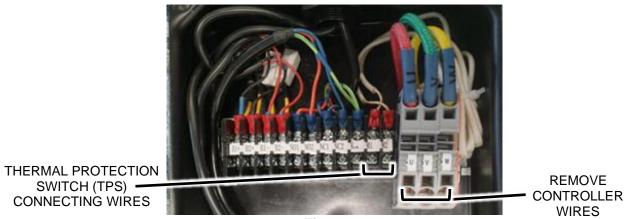


Figure 31

3. On the machine side disconnect the Brake and Brake Switch wires for the brake that is to be worked on (Figure 32).

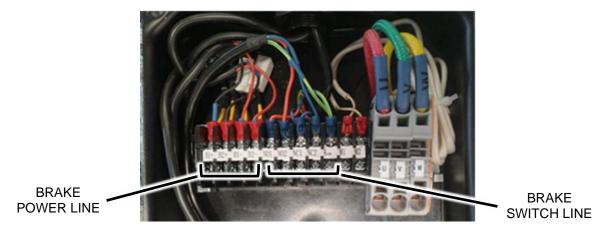
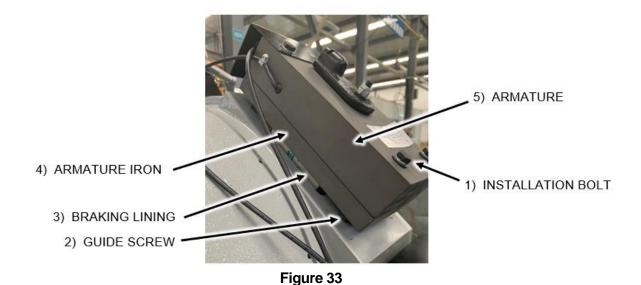


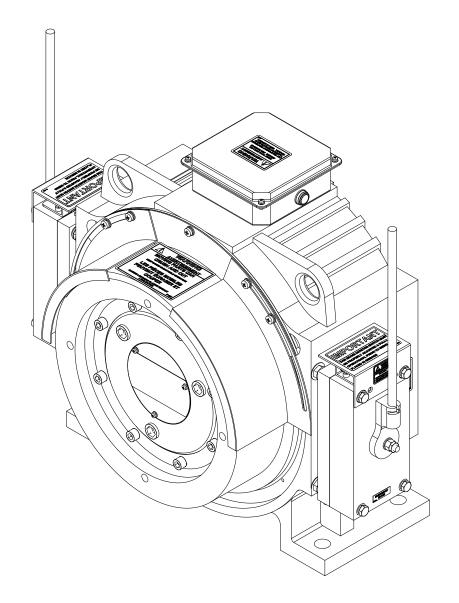
Figure 32

- 4. Use a wrench to loosen the mounting bolt of the installation bolt 1, so that the end face of the guide screw sleeve of the guide screw 2 is separated from the mounting surface of the base.
- 5. Remove the brake and related connecting accessories.
- 6. New or repaired brakes are replaced in the reverse order of the above instructions.
- 7. Adjust the guide screw sleeve of guide screw 2 and the mounting bolt of insulation bolt 1, so that the air gap between the armature of armature 5 and the armature of armature iron 4 is between 0.012" (0.30 mm) to 0.022" (0.55 mm), the gap between the brake belt and the brake wheel is 0.004" (0.10 mm) to 0.006" (0.15 mm), and the distance between the guide screw sleeve of guide screw 2 and the iron surface of armature iron 4 is about 0.197" (5 mm). no less than 0.118" (3 mm) under any conditions, as shown in Figure 33. Brake Installation



7.2.2 Brake Installation

After installation of the brake, please refer to Section 0 to confirm brake is centered and air gap has been restored to factory specifications.



	REPLACEMENT PARTS LIST										
ITEM	QTY	PART NUMBER	DESCRIPTION								
1	1	GLT-25S2-R	GLT-25S2 GEARLESS MACHINE								
1.1	1	GL185-090	BEARING, SEALED SPHERICAL ROLLER								
1.2	1	GLT-25S2-011R	15.75" TRACTION SHEAVE - AS PURCHASED								
1.3	2	GLT-25S2-073	SLEAVE, CONICAL EXPANSION								
1.4	1	GLT-25S2-091	BEARING, DEEP GROOVE BALL								
1.5	1	GLT-25S2-150-LH	BRAKE, GLT								
1.5.1	1	GLT-25S2-150-001	BRAKE, SHOE ASSEMBLY								
1.5.2	1	GLT-25S2-150-003	BRAKE, HANDLE								
1.5.3	1	P-239	LABEL - BRAKE ADJUSTMENT WARNING								
1.5.4	1	P-163	IMPORTANT - BRAKE MONITOR STICKER								
1.5.5	1	GLT-25S2-150-002	BRAKE, SWITCH								
1.6	1	GLT-25S2-150-RH	BRAKE, GLT								
1.6.1	1	GLT-25S2-150-001	BRAKE, SHOE ASSEMBLY								
1.6.2	1	GLT-25S2-150-002	BRAKE, SWITCH								
1.6.3	1	GLT-25S2-150-003	BRAKE, HANDLE								
1.6.4	1	P-163	IMPORTANT - BRAKE MONITOR STICKER								
1.6.5	1	P-239	LABEL - BRAKE ADJUSTMENT WARNING								
1.7	2	GLT-25S2-152	BRAKE DIODE								
1.8	1	GLT-25S2-176	TRACTION SHEAVE GUARD								
1.9	1	ENC-1313	HEIDENHAIN ENCODER ID # 768295-03 "ECN1313 2048 62S12-78"								
1.10	1	P-176	TAG, GEARLESS EMERGENCY BRAKE								
1.11	1	P-184	WARNING LABEL, MOVING PARTS CAN CRUSH AND CUT								
1.12	1	P-221	WARNING LABEL, LIVE CIRCUITS								
1.13	1	P-222	WARNING LABEL, HOT SURFACE								
2	1	GL080-001-04-020	ENCODER CABLE WITH PLUGS - 1.5 METER LENGTH								
3	1	P-230	NAMEPLATE, SMALL, HOLLISTER-WHITNEY								
4	1	P-238	TAG, DATA, MACHINE, CONTRACT								

NOTES UNLESS OTHERWISE SPECIFIED: (C)

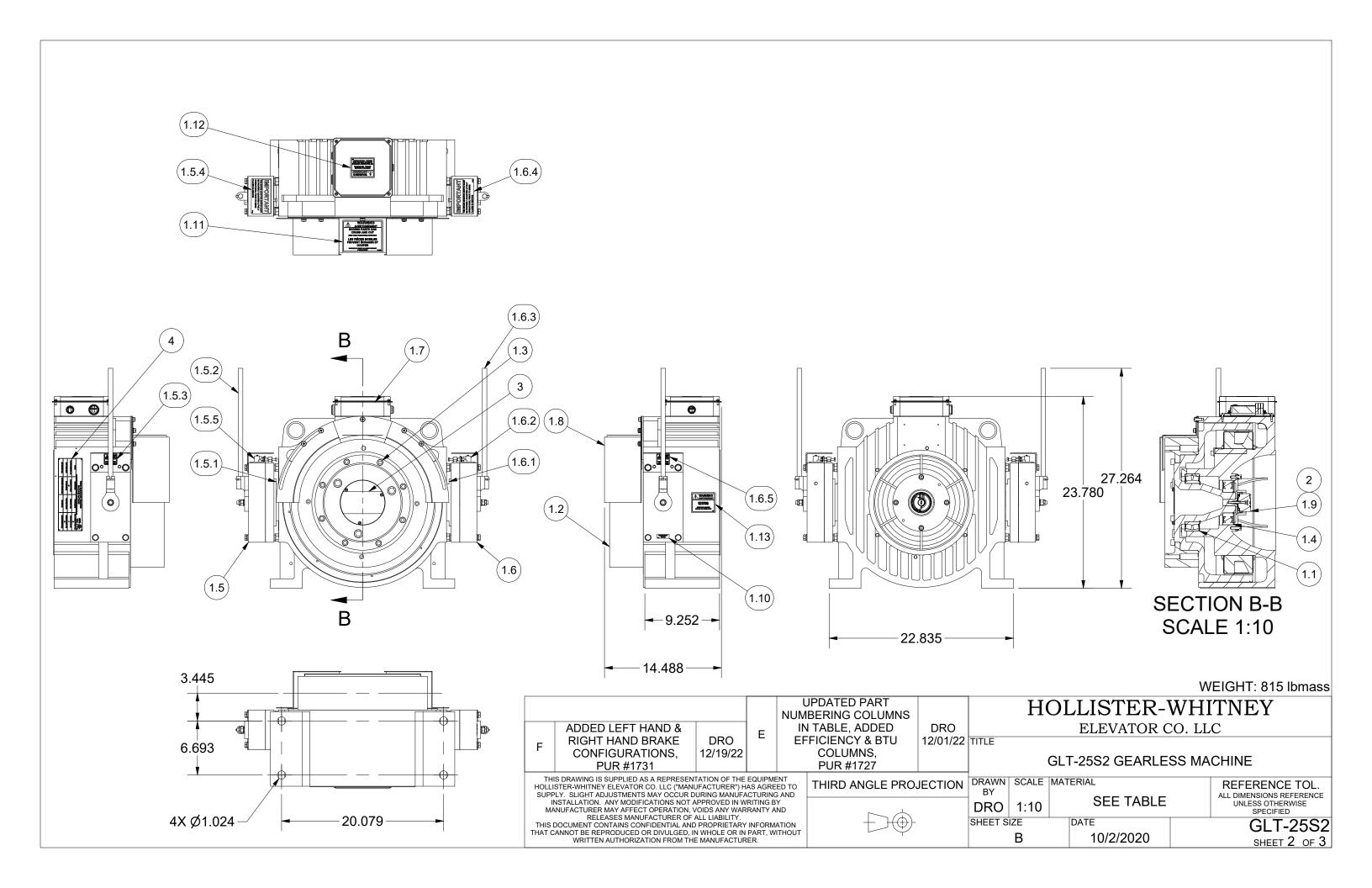
1. RATINGS:

USAGE: SINGLE WRAP, 2:1
WHEEL DIAMETER: 15.75in
VOLTAGE: 380V
SPEED: UP TO 500 fpm
CAPACITY: UP TO 2500#
SHAFT LOAD: 9,000#
SYSTEM LOAD: 18,000#

2. SEE SHEET 3 FOR ADDITIONAL RATINGS CHART.

WEIGHT: 815 lbmass

	ADDED LEFT HAND &		NUM	IBERING COLUMNS TABLE, ADDED	DRO		H(OLLISTER-V ELEVATOR C			
F	RIGHT HAND BRAKE CONFIGURATIONS, PUR #1731	DRO 12/19/22	E	EF	,		TITLE	(GLT-25S2 GEARLES	SS MA	CHINE
HOLLIS SUPP	S DRAWING IS SUPPLIED AS A REPRESEN' STER-WHITNEY ELEVATOR CO. LLC ("MANI LY. SLIGHT ADJUSTMENTS MAY OCCUR D ISTALLATION. ANY MODIFICATIONS NOT A NUFACTURER MAY AFFECT OPERATION, N	UFACTURER") H DURING MANUFA APPROVED IN W VOIDS ANY WAR	IAS AGREE ACTURING (RITING B)	ED TO S AND Y	THIRD ANGLE PRO	JECTION	DRAWN BY DRO	SCALE 1:6	MATERIAL SEE TABLE		REFERENCE TOL. ALL DIMENSIONS REFERENCE UNLESS OTHERWISE SPECIFIED
	RELEASES MANUFACTURER OF , DOCUMENT CONTAINS CONFIDENTIAL AND ANNOT BE REPRODUCED OR DIVULGED, IN WRITTEN AUTHORIZATION FROM THE) PROPRIETARY N WHOLE OR IN	PART, WI				SHEET S	ZE B	10/2/2020		GLT-25S2 SHEET 1 OF 3



					380	V, 2:1,	15.75" \$	SHEAV	E, SINC	GLE WF	RAP						
HOLLISTER- WHITNEY ORDERING PART #	CAPACITY (lbs)	SPEED (fpm)	MOTOR RATING (HP)	MOTOR RATING (kW)	POLES	RATED (rpm)	RATED VOLTAGE	ACTUAL VOLTAGE	RATED FREQ (Hz)	RATED CURRENT (A)	PEAK CURRENT (A)	ESTIMATED EFFICIENCY	MAX BTU/HR	ESTIMATED BTU/HR	RATED TORQUE (ft-lbs)	MAX ACCEL TORQUE (ft-lbs)	CWT (%)
		100	3.7	2.8		48.5		159	12.2			79.1%	1992	637			
GLT-25S2-C-T401	1760	150	5.6	4.2	30	72.7	380	238	18.3	11.8	28.3	83.1%	2412	772	406	812	50
		200	7.5	5.6		96.9		317	24.3			85.2%	2831	906			
		250	9.4	7.0		121.2		220	30.0			86.3%	3270	1046			
GLT-25S2-C-T402	1760	300	11.2	8.4	30	145.4	380	264	36.0	20.1	48.2	87.0%	3732	1194	406	812	50
		350	13.1	9.8		169.7		308	42.5			87.4%	4213	1348			
		400	15.0	11.2		193.9		234	48.6			90.5%	3625	1160			
GLT-25S2-C-T403	1760	450	16.9	12.6	30	218.1	380	263	54.7	30.2	72.5	90.8%	3934	1259	406	812	50
		500	18.7	14.0		242.4		292	60.7			91.1%	4252	1361			
		100	4.5	3.4		48.5		163	12.2			77.0%	2649	848			
GLT-25S2-C-T401	2200	150	6.8	5.1	30	72.7	380	244	18.3	14.3	34.3	81.9%	3131	1002	491	982	50
		200	9.1	6.8		96.9		325	24.3			84.5%	3586	1147			
		250	11.3	8.4		121.2		224	30.0			86.1%	4003	1281			
GLT-25S2-C-T402	2200	300	13.6	10.1	30	145.4	380	269	36.0	24.2	58.1	87.0%	4484	1435	491	982	50
		350	15.9	11.8		169.7		314	42.5			87.7%	4979	1593			
		400	18.1	13.5		193.9		237	48.6			90.3%	4464	1429			
GLT-25S2-C-T403	2200	450	20.4	15.2	30	218.1	380	266	54.7	36.5	87.6	90.8%	4783	1531	491	982	50
		500	22.7	16.9		242.4		296	60.7			91.1%	5109	1635			
		100	5.2	3.9		48.5		170	12.2			75.3%	3276	1048			
GLT-25S2-C-T401	2500	150	7.8	5.8	30	72.7	380	255	18.3	16.4	39.4	80.8%	3824	1224	565	1130	50
		200	10.4	7.8		96.9		340	24.3			83.7%	4318	1382			
		250	13.0	9.7		121.2		228	30.0			85.6%	4762	1524			
GLT-25S2-C-T402	2500	300	15.6	11.7	30	145.4	380	273	36.0	27.9	67.0	86.8%	5262	1684	565	1130	50
		350	18.3	13.6		169.7		319	42.5			87.6%	5772	1847			
		400	20.9	15.6		193.9		242	48.6			90.0%	5315	1701			
GLT-25S2-C-T403	2500	450	23.5	17.5	30	218.1	380	273	54.7	42.0	100.8	90.5%	5643	1806	565	1130	50
		500	26.1	19.4		242.4		303	60.7			91.0%	5977	1913			

NOTES UNLESS OTHERWISE SPECIFIED:

1. BRAKE INFORMATION: PICK VOLTAGE: 110 PICK AMPS: 1.57 HOLD VOLTAGE: 70

HOLD AMPS: 1 2. BRAKE SWITCH NORMALLY CLOSED WHEN BRAKE IS DE-**ENERGIZED**

WEIGHT:

					UPDATED PART IBERING COLUMNS			Н	OLLISTER-	WHI	TNEY
	ADDED LEFT HAND &			IN TABLE, ADDED		DRO			ELEVATOR C	O. LL	C
F	RIGHT HAND BRAKE	DRO	_	EF	FFICIENCY & BTU	12/01/22	TITLE				
	CONFIGURATIONS, PUR #1731	12/19/22			COLUMNS, PUR #1727		GLT-25S2 GEARLESS MACHINE				CHINE
HOI	HIS DRAWING IS SUPPLIED AS A REPRESEN' LISTER-WHITNEY ELEVATOR CO. LLC ("MANU	JFACTURER") H	AS AGRE	ED TO	THIRD ANGLE PRO	DRAWN	SCALE	MATERIAL		REFERENCE TOL.	
	PPLY. SLIGHT ADJUSTMENTS MAY OCCUR D INSTALLATION. ANY MODIFICATIONS NOT A MANUFACTURER MAY AFFECT OPERATION, V	APPROVED IN W OIDS ANY WAR	RITING B	Υ			DRO	ORO SEE TABLE UNLESS O		ALL DIMENSIONS REFERENCE UNLESS OTHERWISE SPECIFIED	
	RELEASES MANUFACTURER OF ALL LIABILITY. THIS DOCUMENT CONTAINS CONFIDENTIAL AND PROPRIETARY INFORMATION THAT CANNOT BE REPRODUCED OR DIVULGED, IN WHOLE OR IN PART, WITHOUT			_					GLT-25S2		
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HEIDENHAIN



Product Information

ECN 1313 ECN 1325 ERN 1387

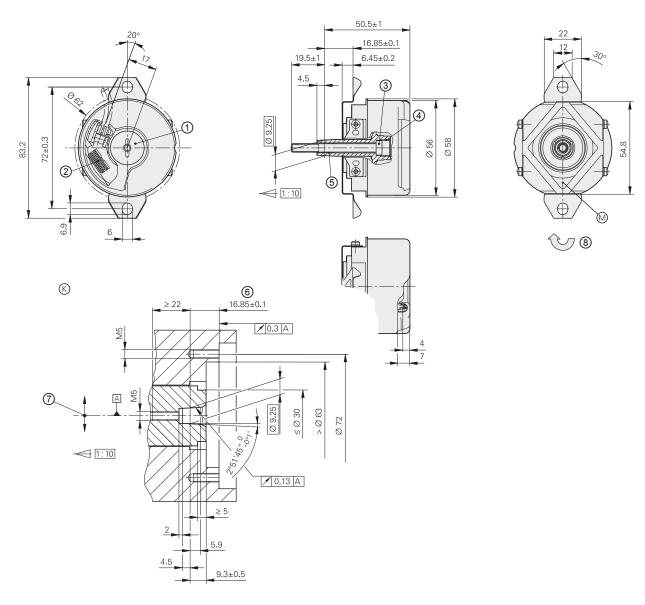
Rotary Encoders with Plane-Surface Coupling for Elevator Servo Drive Control

ECN/ERN 1300 series

Rotary encoders with integral bearings for elevator technology

- Simple installation
- Rigid shaft coupling
- Plane-surface coupling for large mounting tolerances
- Uniform dimensions for various electrical interfaces





Tolerancing ISO 8015 ISO 2768 - m H < 6 mm: ±0.2 mm

- **B** = Bearing of encoder
- © = Required mating dimensions
- ⊕ = Measuring point for operating temperature

 1 = Screw plug, width A/F 3 and 4. Tightening torque: 5+0.5 Nm
- 2 = PCB connector
- $3 = Self-tightening screw M5 \times 50 DIN 6912$ width A/F 4, tightening torque 5+0.5 Nm
- 4 = M10 back-off thread
- 5 = M6 back-off thread
- 6 = Max. permissible tolerance during motor shaft rotation ± 1.5 mm
- 7 = Max. permissible static radial offset of motor shaft in indicated direction ± 0.13 mm
- 8 = Direction of shaft rotation for output signals as per the interface description

	Absolute		Incremental						
	ECN 1325	ECN 1313	ERN 1387						
Part number	683643-xx	768295-xx	749146-xx						
Interface ¹⁾	EnDat 2.2		∼1 V _{PP}						
Ordering designation	EnDat22	EnDat01	-						
Position values/revolution	33554432 (25 bits)	8192 (13 bits)	Z1 track ³⁾						
Electrically permissible speed/error ²⁾	≤ 15000 rpm (for continuous position value)	≤ 1500 rpm/±1 LSB ≤ 12000 rpm/±50 LSB	-						
Calculation time t _{cal} Clock frequency	≤ 7 μs ≤ 16 MHz	≤ 9 µs ≤ 2 MHz	-						
Incremental signals ¹⁾	-	∼1 V _{PP}	∼1 V _{PP}						
Line count/system accuracy	2048/±20"		'						
Reference mark	-		One						
Cutoff frequency –3 dB	-	≥ 400 kHz	≥ 210 kHz						
Electrical connection Via PCB connector	Rotary encoder: 12-pin Temperature sensor ⁴⁾ : 4-pin	12-pin	14-pin						
Voltage supply	DC 3.6 V to 14 V		DC 5 V ±0.25 V						
Power consumption ¹⁾ (maximum)	3.6 V: ≤ 600 mW 14 V: ≤ 700 mW		-						
Current consumption	5 V: 85 mA (typical, without load)		≤ 130 mA (without load)						
Stator coupling	Plane-surface coupling								
Shaft	Taper shaft Ø 9.25 mm; taper 1:1	0							
Mech. permiss. speed n	≤ 2000 rpm								
Starting torque	≤ 0.01 Nm (at 20 °C)								
Moment of inertia of rotor	2.6 · 10 ⁻⁶ kgm ²								
Permissible axial motion of measured shaft ⁵⁾	±1.5 mm								
Radial runout of the measured shaft	0.13 mm								
Vibration 55 Hz to 2000 Hz Shock 6 ms	$\leq 300 \text{ m/s}^2$ (EN 60068-2-6) $\leq 2000 \text{ m/s}^2$ (EN 60068-2-27)								
Operating temperature	-40 °C to +115 °C		-40 °C to +120 °C						
Protection EN 60529	IP40 when mounted								
Mass	≈ 0.25 kg								

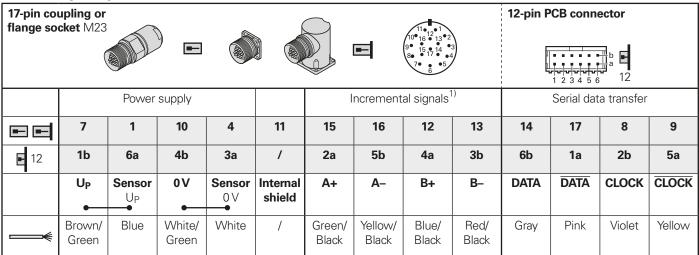
¹⁾ See Interfaces of HEIDENHAIN Encoders brochure
2) Velocity-dependent deviations between the absolute value and incremental signals
3) One sine and one cosine signal per revolution
4) Evaluation optimized for KTY 84-130
5) Compensation of mounting tolerances and thermal expansion, not dynamic motion
6) As per standard for room temperature; for operating temperature

Up to +100 Up to +100 °C: \leq 300 m/s² Up to +115 °C or +120 °C: \leq 150 m/s²

Electrical connection

Pin layouts

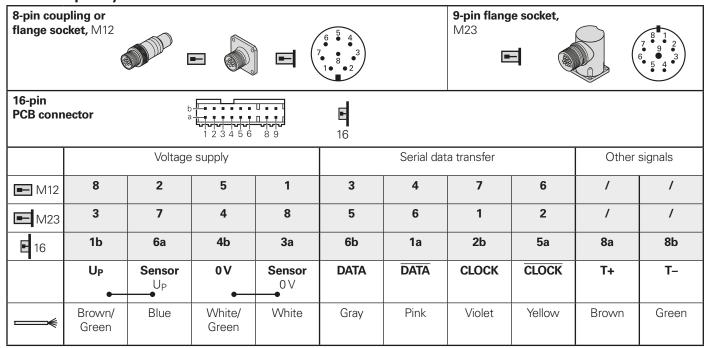
ECN 1313 pin layout



	Other signals							
	5 6							
	/	/						
12	/	/						
	Brown ²⁾	White ²⁾						

Cable shield connected to housing; U_P = Power supply voltage; T = Temperature **Sensor:** The sensor line is connected in the encoder with the corresponding power line. Vacant pins or wires must not be used.

ECN 1325 pin layout



Cable shield connected to housing

 $\mathbf{U_P} = \text{Power supply}; \mathbf{T} = \text{Temperature}$

Sensor: The sensor line is connected in the encoder with the corresponding power line.

Vacant pins or wires must not be used.

¹⁾ Only with ordering designations EnDat 01 and EnDat 02

²⁾ Only for cables inside the motor housing

ERN 1387 pin layout

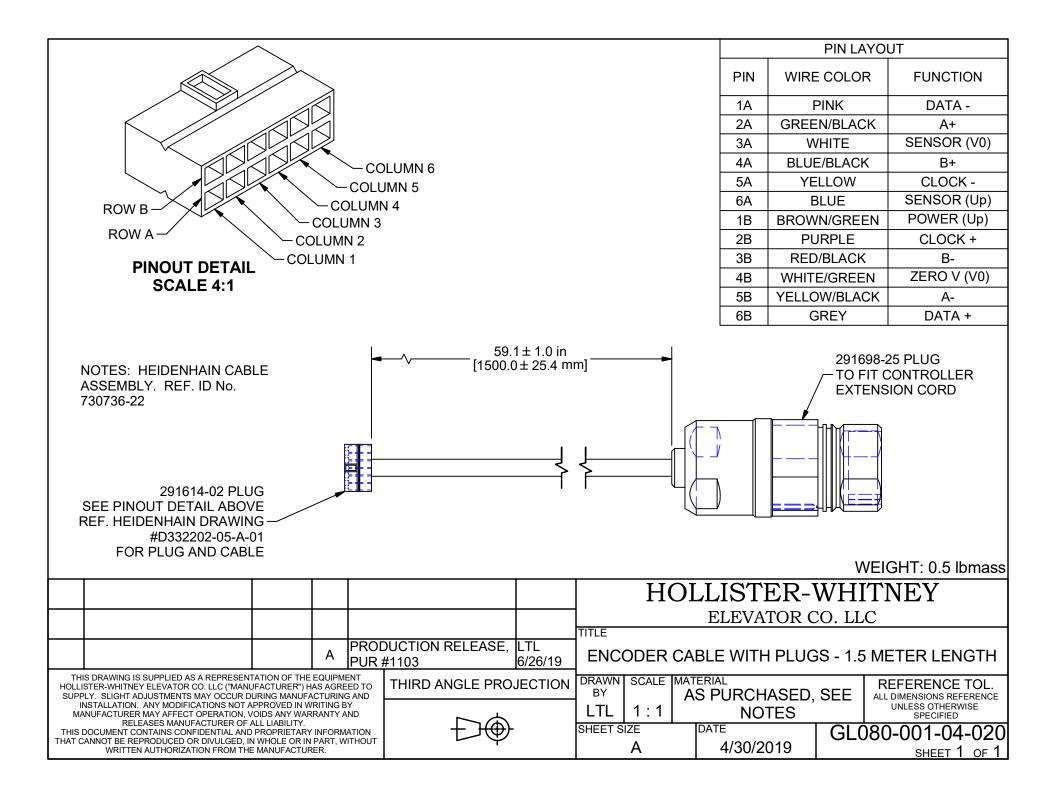
17-pin con flange so							110 12 10 16 16 9 15 8 0 17	1 13 • 2 14 • 3 14 • 4 • 5	14-pin PC	B connecto	• • b
		Voltage	supply					Incremen	tal signals		
	7 1 10		4	11	15	15 16 12			3	2	
E	1b	7a	5b	3a	/	6b	2a	3b	5a	4b	4a
	U _P	Sensor U _P	0 V •—	Sensor 0 V	Internal shield	A+	A –	B+	B-	R+	R-
\	Brown/ Green	Blue	White/ Green	White	/	Green/ Black	Yellow/ Black	Blue/Black	Red/Black	Red	Black

	Other signals												
	14	17	9	8	5	6							
E	7b	1a	2b	6a	/	/							
	C+	C-	D+	D-	T+ ¹⁾	T – ¹⁾							
	Gray	Pink	Yellow	Violet	Green	Brown							

Cable shield connected to housing;

Up = Power supply; T = Temperature
Sensor: The sensor line is connected internally with the corresponding power line.
Vacant pins or wires must not be used.

¹⁾ Only for cables inside the motor housing



general tolerance

⊃aßmaß

Name

Abmaß

Tolerancing

Keine Maße aus der Zeichnung abnehmen/Do not scale

Surface details

Stiftsteckverbinder: SUB-D 15 pol. Kabel: $4 \times (2 \times 0.14) + 2 \times (0.5)$ Buchsensteckverbinder: Metallgehäuse mit Metallgehäuse mit Schirmanbindung Geeignet für Energieführungsketten Schirmanbindung, Kontaktbuchsen Gehäusebreite max 31 mm Dauerbetriebstemperatur 80 Grad Ölbeständig Hersteller 1 : Intercontec Farbe orange RAL 2003 : ASTA 035 FR 11 12 0005 000 Тур CABLE LENGTH UP TO 30 M Hersteller 2 : Interconnectron SPN A 17B NN NN 169 Тур Hersteller 3 : Coninvers : RC-17 S1N8A R300 Тур **SCHIRM** DETAIL X Kabelkennzeichnung mit KEB Art. Nr. auf dem Kabelmantel an beiden Steckerseiten. Bei Längen unter 1m nur einseitig. Kabelmantel muß bis in das Innere Abschirmungen nicht kontaktieren. Steckergehäuse mit Steckergehäuse geführt werden. 4 Nm verschrauben. Lötkontakte im Stecker mit (Isoliert gegeneinander und gegen äußeren Schirm.) Schrumpfschlauch isolieren. rot (B-) RED blau (B+) BLUE gelb (A-) YELLOW grün (A+) GREEN ANSICHT KABELSEITE violett (Takt-) VIOLET (CLOCK -) schwarz (Takt+) BLACK (CLOCK +) BLUE blau (B+) 11 WHITE weiß (GND) (10) 5 3 2 2 DETAIL X SUB-D 15 POL: 12 ANSICHT VON KABELSEITE YELLOW gelb (A-) rot (B-) RED 7 8 10 9 6 (16) (13) 9 (CLOCK-) VIOLET violett (Takt-) 3 Äußeren Schirm an Metallgehäuse (17) (13) (12)(15) (14) (11) des SUB-D löten! grau (Data+) GRAY GREEN grün (A+) (15) 8 (CLOCK+) BLACK schwarz (Takt+) 4 braun (5V) BROWN rosa (Data-) PINK weiß und alle Innenschirme (GND) WHITE 7 5 BROWN braun (5V) 6 rosa (Data-) PINK grau (Data+) GRAY 00.F5.0C1-4xPx KABELLAENGE METER X,X 00.F5.0C1-4xxx KABELLAENGE **METER** XXX Kantenbruch/Break of sharp edges Werkstoff: /Material: Rohteil-Nr.: /Blank-No.: Benennung: /Title Rohmaß:/Rough size Ident-Nr.: Menge: /Qty. Geberkabe verzinkt, blau passiviert Schichtdicke: Schutzvermerk DIN 34 beachten úm Zeichnungs-Nr.: /Drawing No.: Datum Name Rz 100 Observe protection note DIN 34 zinc-plated, blue passivated / Thickness of coat: 5.04.02 Horn 4005 Oberfilchenangaben Allgemeintoleranz Werkstickkanten Rz 25 Tolerierung ISO 8015 DIN 6930-m DIN ISO 1302 DIN 6784

Workpiece edges

Alle MaBe in Millimeter/All dimensions in millimetres

Maßstab

Scale

Karl E. Brinkmann GmbH

D 32677 Barntrup

Rz 6.3

geschliffen/ground

Rz 4

Stiftsteckverbinder: SUB-D 15 pol.

Metallaehäuse mit Schirmanbindung

Gehäusebreite max 31 mm

CABLE LENGTH OVER 40 METERS Hersteller 2 : Interconnectron : SPN A 17B NN NN 169 Hersteller 3 : Coninvers : RC-17 S1N8A R300 DETAIL X **SCHIRM** Kabelkennzeichnung mit KEB Art. Nr. auf dem Kabelmantel an beiden Steckerseiten. Bei Längen unter 1m nur einseitig. Kabelmantel muß bis in das Innere Abschirmungen nicht kontaktieren. Steckergehäuse mit Steckergehäuse geführt werden. 4 Nm verschrauben. Lötkontakte im Stecker mit (Isoliert gegeneinander und gegen äußeren Schirm.) Schrumpfschlauch isolieren. violett (B-) VIOLET blau (B+) BLUE braun (A-) BROWN (0.25mm wire) grün (A+)GREEN ANSICHT KABELSEITE rot (Takt-) RED schwarz (Takt+)BLACK BLUEblau (B+) WHITE weiß (GND) 10 3 2 DETAIL X SUB-D 15 POL: 2 5 ANSICHT VON KABELSEITE BROWN (0.25mm wire) braun (A-) violett (B-)VIOLET 9 (10) 8 6 16 9 RED rot (Takt-) 3 Äußeren Schirm an Metallgehäuse (17 (13)**1**5 (11) des SUB-D löten ! GREEN grün (A+) grau (Data+)GREY (15) 8 BLACK schwarz (Takt+) braun (5V) BROWN (1.0mm wire) rosa (Data-) PINK weiß und alle Innenschirme (GND) WHITE 7 5 braun (5V) 6 rosa (Data-) PINK BROWN (1.0mm wire) grau (Data+) GREY 00.F5.0C1-LxPx KABELLAENGE **METER** X.X 00.F5.0C1-Lxxx KABELLAENGE **METER** XXX Rohmaß: /Rough size: Ident-Nr.: Menge: /Qty.: ME Werkstoff: /Material: Rohteil-Nr.: /Blank-No.: Benennung: /Title Kantenbruch/Break of sharp edge: Anderungen:/Modifications Geberkabel verzinkt, blau passiviert Schichtdicke: Schutzvermerk DIN 34 beachten úm Zeichnungs-Nr.: /Drawing No.: Datum Name Rz 100 zinc-plated, blue passivated / Thickness of coat: Observe protection note DIN 34 15.06.07 Horn gez.: Werkstickkanten Rz 25 Allgemeintoleranz Oberfilchenangaben Tolerierung ISO 8015 DIN 6930-m DIN ISO 1302 DIN 6784 Format Size Maßstab Rz 6,3 general tolerance Tolerancina Surface details Workpiece edges Karl E. Brinkmann GmbH Scale chliffen/ground Paßmaß Size of fit Keine Maße aus der Zeichnung abnehmen/Do not scale Alle MaBe in Millimeter/All dimensions in millimetres D 32677 Barntrup Name

Kabel: $(4 \times (2\times0,25) + 2 \times 1,0)$

Geeignet für Energieführungsketten

Aderfarbkode nicht nach DIN 47100

Helukabel Topgeber 510 77750

Buchsensteckverbinder:

Hersteller 1

Tvo

Metallaehäuse mit

: Intercontec

Schirmanbindung, Kontaktbuchsen

: ASTA 035 FR 11 12 0005 000



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