

GLV-40S1 Gearless Machine Instruction Manual (#1196)



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This installation and service manual is intended for the use of qualified and authorized elevator personnel ONLY. For your safety and the safety of others, do not attempt ANY procedure that you are not qualified and authorized to perform. Recommended procedures must be done in accordance with the applicable rules of the latest edition of the National Electrical Code; the latest edition of ASME A17.1; and all governing local codes. Every attempt has been made to ensure that this guide is accurate and up to date. Hollister-Whitney Elevator Co. LLC assumes no liability for consequences resulting from any error or omission. Please notify Hollister-Whitney Elevator Co. LLC regarding any difficulties with this guide.

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1 Introduction

1.1 Description

Thank you for choosing the Hollister-Whitney Elevator Corporation's (HWEC), GLV-40S1 Gearless Machine!

The GLV-40S1 machine has been designed for use in 1:1 roped machine room applications with VVVF controls. The machine is designed with 30 poles to provide smooth, quiet, and long-lasting operation.

HWEC machines are designed to perform in a tolerant machine space. The machine space working temperature should be held between 35° F & 104° F, (1.7° C & 40° C) and humidity should be held to an average of 90% non-condensing.

1.2 Warranty Information

All parts and equipment manufactured by HWEC are guaranteed against defects in material and workmanship for a period of one (1) year from the date of shipment.

Warranty covers only the repair or replacement of parts, F.O.B. our factory, upon determination by inspection at our factory that warranty is applicable.

Equipment and components not of our manufacture are warranted only to the extent of the original manufacturer's warranty.

Our warranty specifically does not include any other incidental liability or expense such as transportation, labor, and unauthorized repairs.



2 Safety Precautions

Read this section before any work is performed on elevator equipment.

***** IMPORTANT –

The procedures contained in this manual are intended for the use of qualified elevator personnel. In the interest of your personal safety and the safety of others, do NOT attempt ANY procedure that you are NOT qualified to perform.

All procedures must be done in accordance with the applicable rules in the latest edition of the National Electrical Code; the latest edition of ASME A17.1; and any governing local codes.

2.1 Terms in This Manual

CAUTION:

Caution Statements identify conditions that could result in damage to the equipment or other property if improper procedures are followed!

WARNING:

Warning Statements identify conditions that could result in personal injury if improper procedures are followed!

2.2 General Safety

Specific warnings and cautions are found where they apply, and DO NOT appear in this summary.

2.3 Electrical Safety

All wiring must be in accordance with the National Electrical Code and must be consistent with all state and local codes.

2.4 Electrical Hazards

Electric shocks can cause personal injury or loss of life. Circuit breakers, switches and fuses may NOT disconnect all power to the equipment. Always refer to the wiring diagrams. Whether the A/C supply is grounded or not, high voltage will be present at many points.

2.5 Mainline Disconnect

Unless otherwise suggested, always turn OFF. Lock and Tag out the mainline disconnect to remove power from the equipment.

2.6 Test Equipment Safety

Always refer to manufactures' instruction book for proper test equipment operation and adjustments.

Megger testing, or buzzer type continuity testers, can damage electronic components. Connection of devices such as voltmeters on certain low-level analog circuits may degrade electronic system performance. Always use a voltmeter with a minimum impedance of 1M Ohm/Volt. A digital voltmeter is recommended.

2.7 When Power Is On

Dangerous voltages exist at several points in some products. To avoid personal injury, do NOT touch exposed electrical connections or components while power is On.

2.8 Product Specific Warnings

V WARNING

GLV-40S1 series machines MUST be balanced during hoisting. See paragraph 3.4 for proper lifting configurations.

V WARNING

Hang the elevator car before removing ANY bolts. Failure to do so may result in severe injury and equipment damage.



3 Arrival of the Equipment

3.1 Receiving

Immediately upon arrival of the machine, make a visual check for any external damage. If any damage incurred in transit is found, make notice of the claim in the presence of the carrier, and notify HWEC. If necessary, do not put these machines into operation without first consulting HWEC.

If the machine has gotten wet during transportation, make notice of the claim in the presence of the carrier and notify HWEC. See also Section 3.6.

3.2 Data Tag

Check the machine data tag to ensure the machine conforms to your order.

Hallister- Whitney A VINTAGE Company MA	PMAC ELEVAT MACHINE F NUFACTURED IN COOPERATION WITH SHENYAN	RATINGS	CSA B44.1 ASME A17.5 CO., LTD 155941 C
MODEL	SUSPENSION	POWER (hp/KW)	MAX. AMBIENT TEMP (°C) 40
CONTRACT/SERIAL NO.	NUMBER OF POLES 30	FREQUENCY (Hz)	INSULATION CLASS F
CAR SPEED (fpm)	TORQUE (ft-lbs)	VOLTS (V) / PHASES	ELEVATOR DUTY (%) 50
CAR CAPACITY (lbs)	ROTATIONAL SPEED (rpm)	CURRENT (A)	MACHINE WEIGHT (lbs)



Figure 1

3.3 Handling

The machine will be delivered on a wooden pallet. It can be left on the pallet and moved with a standard fork truck or pallet jack.

3.4 Hoisting

The machine weighs about 4500 pounds (2040 kg). When removing the machine from the pallet, it must be lifted using the lifting holes provided at the bottom of the machine.

When lifting the machine, use a spreader beam or other suitable rigging device to pull straight up on the lifting holes.

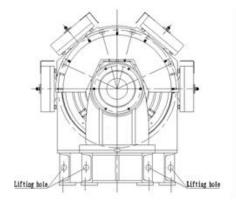


Figure 2

WARNING

Use only the hoisting method shown when lifting the machine! Do not use any other machine component to lift the machine! Lifting the machine by any other component will result in damage to the machine or possible failure of the component resulting in the machine falling from the hoisting system!

Follow all the necessary precautions to avoid damage to the machine or risk to personnel when moving or hoisting the machine.

3.5 Storage

During storage in a warehouse or on the elevator job site, precautions must be taken to protect the machine from dust, dirt, moisture, metal shavings and temperature extremes.

For short term storage, place the machine in a warm, dry and clean environment.

Protect the machine from harsh weather conditions and temperature variations that can lead to condensation.

Protect from dust and metal shavings. Metal dust and shavings can be attracted into the machine by the magnets.

For longer term storage, follow the recommendations above plus; place the machine in a sealed, waterproof enclosure. Add a dehydrating packet that is sized for the enclosure's volume and humidity level.

3.6 Moisture, Condensation

Before installing the machine, and before any voltage is applied, check the machine for condensation, or any evidence of moisture or water. If any evidence of wetness is found, contact HWEC for drying instructions.

After the machine has been dried per factory instructions, it will be necessary to verify the insulation between each coil phase and earth ground. Using an insulation tester (or megohmmeter) check the insulation resistance at 500VDC. The resistance should be NO LESS than 100 Mohm.



4 Application

4.1 Overview

The GLV-40S1 series machine is a synchronous permanent magnet gearless machine designed for elevators. The machine has 30 poles to provide smooth, quiet, and long-lasting operation. Its configuration allows elevator capacity up to 4000 lbs. with 1:1 roping, single wrap arrangement at 50% counterbalance with up to a 22000 lb. shaft load. See Section 4.4 below for complete specifications. The overall system load is calculated by adding the following items:

Empty Car Weight + Counterbalance Weight + Capacity + Hoist Rope Weight + Compensation Weight + Traveling Cable Weight

The GLV-40S1 machine brake system uses four block brakes.

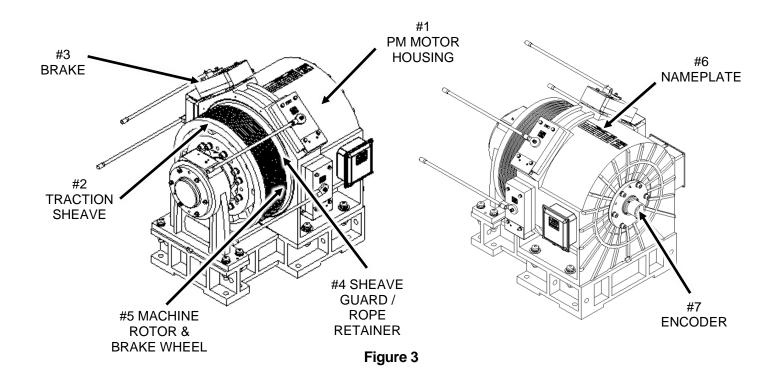
The latest HWEC manuals, bulletins and procedures are available for download from the HWEC website.

The following is a list of major components of the GLV-40S1 machines. Along with a description of their functions, there is an overview of some of the critical adjustments and maintenance information. See Installation and Maintenance for detail.

- 1. **PM Motor Housing** The housing contains the PM windings used to provide the necessary torque and speed to move the elevator in operation.
- 2. **Traction Sheave** A grooved sheave is connected directly to the machine rotor. The grooves provide traction between the sheave and the hoist ropes.
- 3. **Brake** The electromechanical device is used to prevent the elevator from moving when the car is at rest.
- 4. **Sheave Guard/Rope Retainer** Provides rope retention and keeps hoist ropes away from contact after rope installation.
- 5. **Machine Rotor & Brake Wheel** The brake wheel is connected to the main shaft. When the brake is energized, the brake is released from the brake wheel.
- 6. **Nameplate** Displays the machine rated data and manual factory contact/serial number information.
- 7. **Encoder** (Behind Cover) This device is directly coupled to the rotor of the machine. It is provided to give the absolute speed feedback of the hoist motor to the inverter drive system and to the elevator controller.

BULLETIN

GLV-40S1 #1196 GEARLESS TRACTION MACHINE



4.2 Codes and Standards

These machines are designed to comply with ASME A17.1/CSA B44 code. The motors are designed with insulation class F minimum and have been approved by and carry a CSA approved label.

4.3 Environmental Specifications

- Operating ambient temperature: 35° F to 104° F (1.7 C to 40 C)
- Humidity average of 90% non-condensing

4.4 Machine Specifications

- Traction Sheave (removeable) Diameter: 20 in or 25 in
- Main and emergency disc brakes, each capable of holding 125% of the load.
- Brake switches, wired normally close standard.
- Heidenhain ECN1313 2048 encoder and 1.5-meter-long cable (standard)
- Sheave guard/rope retainer.
- Machine dimensions and parts list can be found at the end of this book.

					m	80V, 25	" Whee	, 1:1 Si	igle Wra	p Up to	4,000# ci	apacity, U	Ip to 500) fpm, 2	2000# Shi	380V, 25" Wheel, 1:1 Single Wrap Up to 4,000# capacity, Up to 500 fpm, 22000# Sheave Shaft Load	bad				
HW Ordering Part #	Supplier Part #	Capacity (Ibs)	Speed (fpm)	Motor Rating (HP)	Motor Rating (kW)	۵	Rated (rpm)	Rated / Voltage V	Actual R Voltage Fre	Freq(Hz) Cu	Rated Current(A) C	Peak Current (A)	Efficiency		Pr de	Rated Torque(ft-lbs)	MaxAccel Torque(ft-lbs)	٥	Sheave Dia(")	Motor Winding Specification	Brake Information
		2500	100 150	5.1	3.8 5.7	30 30						40.1	80.6% 85.2%	2531 2903	810 929	1764		50	25 25		
			200	10.3	1.7	30	30.6	380	312.0	L.T	16.7	40.1	87.6%	3244	1038	1764	3528	50	25		
		0000	100	6.0	4.4	8	15.3	380	158.2	3.9	19.3	46.3	78.2%	3328	1065	2048	4096	ន	Я ;		
		0005	000	011	000	8	30.6	380	216.0	2.0	10.3	40.3	84.U%	30/3	1277	2048	4096	R 5	d X		
GLV-4051-C-VS401B	WYT V1S 1.0EF5635 VS401B		100	1.1	5.3	90	15.3		5.9.5	3.9	23	55.2	76.2%	4269	1366	2428	4856	3 3	25	WYT V15.1.1 VS401B	
		3500	150	10.6	7.9	30	22.9	380	239.3	5.8	23	55.2	82.1%	4818	1542	2428	4856	8	25		
			200	14.1	10.5	30	30.6	380	319.0	2.7	23	55.2	85.4%	5261	1684	2428	4856	8	25		
		0000	100	7.9	5.9	8	15.3	380	165.5	3.9	25.8	61.9	74.4%	5168	1654	2731	5462	ន	22		
		4000	200	15.9	11.8	30	30.6	380	331.0	2.7	25.8	619	84.3%	6331	2026	2731	5462	8 8	2		
			250	12.8	9.6	30	38.2		211.4	9.6	28.6	68.6	88.7%	3691	1181	1764	3528	8	25		
		2500	300	15.4	11.5	30	45.8	380	253.7	11.6	28.6	68.6	89.5%	4101	1312	1764	3528	8	25		Brake Part Number:
			350	18.0	13.4	30	53.5	380	296.0	13.5	28.6	68.6	90.1%	4507	1442	1764	3528	8	25		D1D 110RB
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		3500	300	21.2	15.8	8	45.8	380	1/5	11.6	39.3	94.3	88.6%	6150	1968	2428	4856	3	22		110, 1.98
			350	24.7	18.4	30	53.5	380	100.00	13.5	39.3	94.3	89.5%	6590	2109	2428	4856	3	25		Hold Volts, Amps:
			250	19.9	14.8	30	38.7	380	210	96	44.7	106.1	86.6%	6797	2175	731	6985	5	×		70, 1.26
		4000	300	23.8	17.8	R	45.8	380	165.7	11.6	44.2	106.1	88.0%	7279	2329	2731	5462	3	n N		
			350	27.8	20.7	30	53.5	380	10.0	13.5	44.2	106.1	89.1%	7740	2477	2731	5462	3	22		
			400	20.5	15.3	30	61.1	380	32.8	15.2	41.4	99.4	90.5%	4938	1580	1764	3528	50	25		
		2500	450	23.1	17.2	8	68.8	380	1619	171	41.4	99.4	90.9%	5367	1718	1764	3528	3	25		
			2005	25.7	191	30	76.4	380	016	0.6	41.4	99.4	91.1%	5809	1859	1764	3528	8	X		
			400	23.8	17.8	8	61.1	380	33.5	15.2	48	115.2	90.3%	5874	1880	2048	4096	8	25		
		3000	450	26.9	20.0	30	68.8	380	52.3	171	48	115.2	90.6%	6434	2059	2048	4096	S	25		
			500	29.9	22.2	30	76.4	380	92.0	0.6	48	115.2	91.3%	6619	2118	2048	4096	S	25		
GLV-4051-C-V5403B	WYT-V15-2.5EF5635-V5403B		400	28.3	21.1	30	61.1	380	34.4	15.2	57	136.8	90.1%	7102	2273	2428	4856	8	25	WYT-VIS.1.1-VS403B	
		3500	450	31.8	23.7	8	68.8	380	363.7	17.1	57	136.8	90.7%	7556	2418	2428	4856	S	25		
			005	35.3	263	30	76.4	380	193.0	061	6	136.8	91 1%	8018	7566	7478	4856	5	s,		
			400	31.8	23.7	8	61.1	380	138.4	65	18	153.6	89.8%	8277	2648	2731	2462	9	s S		
		4000	450	35.8	26.7	8	68.8	380	168.2	121	3	153.6	90.4%	8744	2798	2731	5462	8	2		
			200	39.7	29.6	30	76.4	380	38.0	19.0	8	153.6	90.9%	9218	2950	2731	5462	8	R		
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						SUV, 20	Wheel	1:1 SIN	gle Wrat	0 Up to 4	t,000# ca	apacity, U	o to 500	tpm, 22	000# She	380V, 20" Wheel, 1:1 Single Wrap Up to 4,000# capacity, Up to 500 tpm, 22000# Sheave Shaft Load	pe				
HW Ordering Part #	Supplier Part #	Capacity	Speed	Motor Basing (UD)	Motor Basicon (1440	Poles	Rated R	Rated Ac	Actual Rat	Rated Ra	Concepted	Peak E	Estimated	Max	e tri Accelerated	Rated Torono(6-lbo)	MaxAccel Torono/6-16-1	Cwt(%)	Sheave	Motor Winding	Brake Information
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		_	200	10.2	7.6	8	38.2	30	2.0 9	5	121	41.0	88.4%	3020	996	1409	2818	8	8		
			8	6.0	4.4	30	19.1	88	8.0 4		6.61	47.8	81.4%	2840	506	1639	3278	8	8		
		3000	150	6.8	6.7	90	28.6	80	63 7	2	6.61	47.8	85.7%	3238	1036	1639	3278	9	20		
		_	200	611	6.8	8	38.2	380	54		19.9	47.8	87.2%	3876	1240	1639	3278	8	8		
GLV-4051-C-VS401A	WYT-V1S-1.0EFS508-VS401A		8	7.1	53	8			95) 00	33.6	56.6	79.2%	3742	1197	1941	3882	3 3	1	WYT-V1S.1.1-VS401A	
		3500	150	10.6	2.9	90	28.6	380	9.3 7	2	23.6	56.6	84.2%	4261	1363	1941	3882	8	20		
			200	14.1	10.5	8	38.2	380	9.0	5	23.6	56.6	86.9%	4718	1510	1941	3882	9	20		
			8	2.9	5.9	30		380	55	4.8	26.5	63.6	77.6%	4527	1449	2185	4370	8	8		
		4000	150	11.9	8.9	30	28.6	380	8.3 7.	2	26.5	63.6	83.1%	5126	1640	2185	4370	9	20		
			200	15.9	11.9	8	38.2	380 33	10 9	5	26.5	63.6	86.1%	5628	1801	2185	4370	8	20		
			250	12.8	9.6	8	47.7	80 2	1.4 12	0	30.3	72.7	91.3%	2844	910	1409	2818	50	8		
		2500	300	15.4	11.5	30	57.3	380 22	3.7 1A	1.4	30.3	72.7	92.2%	3042	973	1409	2818	50	20		Brake Part Number:
			350	17.9	13.4	90	66.8	380 2	36.0 16	5.8	30.3	72.7	92.9%	3242	1038	1409	2818	50	20		D1D 110RB
			250	14.8	11.1	8	+	380	3.2 15	0	35.3	84.7	90.5%	3577	1145	1639	3278	8	20		
		00000	80	17.8	13.3	8	+	380	5.2	4	35.3	84.7	91.4%	3895	1246	1639	3278	8	8		Brake Oty:
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			250	17.6	13.2	8	47.7	380	13	4	41.8	100.3	89.4%	4752	1521	1941	3882	3	Т		Pick Volts, Amps:
		3500	8	21.2	15.8	8	4		_	14.4 4	41.8	100.3	90.7%	4988	1596	1941	3882	8	20		110, 1.98
			350	24.7	18.4	8	~	380	300.0	8	41.8	100.3	91.7%	5217	1669	1941	3882	8	20		Hold Volts, Amps:
			250	19.9	14.8	8	47.7	380 2	21.4 1.	2	47	112.8	88.5%	5790	1853	2185	4370	8	20		70, 1.26
		4000	8	23.8	17.8	8	5/3	88	1	4	47	112.8	30.0%	6051	1936	2185	4370	3	20		
			ŝ	27.8	20.7	8	898	88	1000	2	47	112.8	91.1%	6238	2015	2185	4370	8	8		
			40	20.5	15.3	8	76.4	380	32.8 11	0.0 4	40.9	98.2	90.9%	4750	1520	1409	2818	ន	50		
		2200	420	23.1	17.2	8	+	280	Z 2.	4	40.9	98.2	91.1%	873	1004	1409	2818	8	8		
			3	0.0	161	R 8	ŝ		10		505	7.85	91.5%	80	7191	1409	2010	8 8	8 8		
		_	a	0.07	11.0	R 8	4.07				41.0	7.611	20.076	1/00	1/02	6001	0/70	8 8	8		
		8	600	0.02	0.02	8 8	2.00	7 100			47.0	7.611	81.578	5525	1005	6501	0/70	8 8	8		
GLV-4051-C-V5403A	WYT-V1S-2.5EF5508-V5403A			0.67	7.77	8 8	2	100	770		47.0	7-611	24-16	1700	1007	5001	0/70	8 8	8 8	WYT-V1S.1.1-VS403A	
		3500		318	73.7	8 8	-	-	53.7 21		56.4	135.4	201.75	7127	V3CC	THET	7000	8 9	8 8		
			6 g	35.3	1.62	8 8		-	20 00	* *	10.4	135.4	N1.6%	/61/	2420	1941	7000	R 8	8 8		
			8	318	73.7	8 8	76.4	3 180	01 V8.		5.55	152.4	201.4%	7730	2474	2185	4370	8 5	07		
		4000	450	35.8	26.7	t		180	82 21	4		┢	91.0%	\$212	2628	2185	4370	8	0		
			8	39.7	29.6	8	5.55	380	298.0 23	9	63.5	152.4	91.4%	8703	2785	2185	4370	ន	2		
-						-	_		-					01.00	Ar an	-					

Table 1 Maximum Detailed Specifications

BULLETIN

4.5 Brake Specification

- Four brakes are supplied standard from the factory. Two brakes are meant to serve as a primary machine brake and the other two brakes as a secondary emergency brake. Please contact Hollister-Whitney for details regarding using a Rope Gripper[®] as the emergency brake with a GLV-40S1 machine.
- Brake switch rating DC 110 V Rated current 1.98 A.
- The opening voltage of the brake is not more than 110 V, the releasing voltage is not more than 70 V, and the control range is 15 V-30 V.
- The machine brakes are mounted in 4 locations as shown in Figure 4.

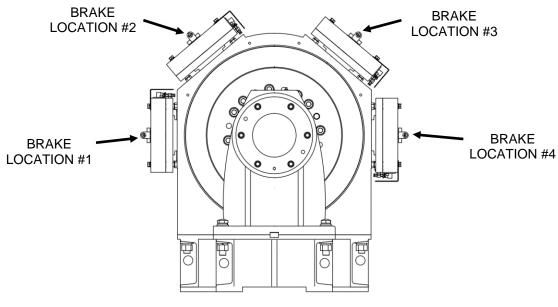


Figure 4



5 Installation

5.1 Machine Mounting

Before hoisting the machine into place, verify all the hoisting equipment is rated for the 4500 pounds (2040 kg) weight of the machine. See Section 3.4

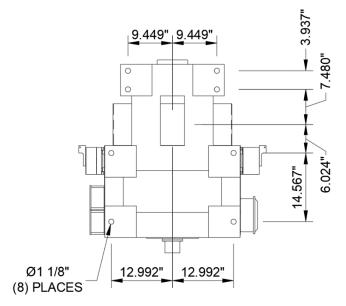
Provide a level, structurally supported (rated for the load on the machine) machine space with proper clearance around the machine for maintenance and adjustments.

This machine is primarily intended to be mounted in traditional overhead applications with down-pull forces on the traction sheave.

5.1.1 Traditional Overhead Mounting

Anchor the machine to the structural support surface using the (8) mounting hole locations in the base. The hardware required to anchor the machine to the support surface should be at least 1" diameter, grade #5 minimum, with standard washers. Hardware adhering to ASME A325 is also suitable.

Note - Due to the varying mounting surface thicknesses, no mounting hardware is shipped with the machine.





BULLETIN

GLV-40S1 #1196 GEARLESS TRACTION MACHINE

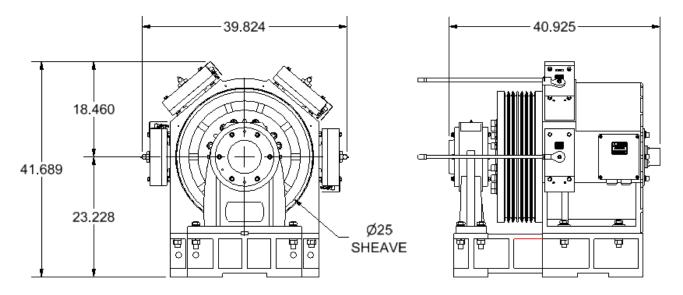


Figure 6

5.2 Electrical Connection

Use the project wiring diagrams (with the motor configuration information) to connect the motor to the controller.

WARNING

Before performing any electrical connections, make sure that power supply is turned off. Only then proceed with connecting electrical leads to power supply. Never work in machine electrical enclosure while power supply is on!

Direct connection to the three-phase power is forbidden, it may destroy the motor.

5.2.1 Machine Wiring

- The Thermal Protection Switch (TPS) is wired with leads labeled and supplied into the machine electrical enclosure. Refer to Figure 7.
- Consult your controller manufacturer for appropriate TPS connections.
- Verify the electrical supply from the elevator drive and brake power supplies match the machine data tag. Refer to Figure 1.

BULLETIN

GLV-40S1 #1196 GEARLESS TRACTION MACHINE

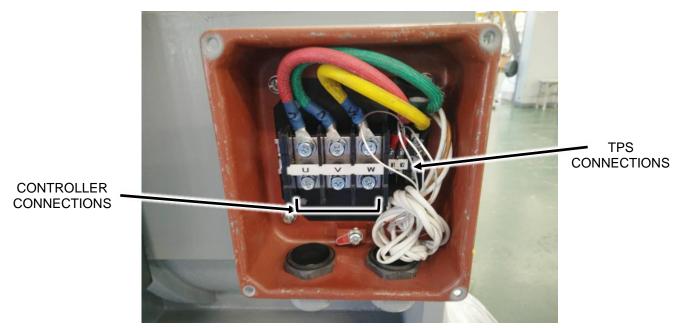


Figure 7

- Connect the U-V-W lines from the drive as shown.
- Earth Ground connects to the ground lug terminal inside the electrical enclosure.

Note - Check and tighten all leads (motor side and line side) on installation.

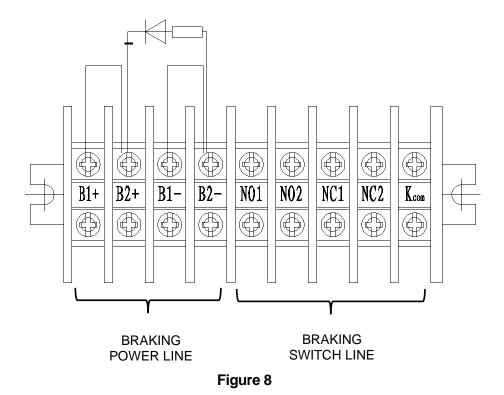
WARNING

The machine and emergency brake coils must be independent!

It is the responsibility of the user to connect the motor in accordance with the current laws and regulations in the country of use. This is particularly important regarding wire sizes used to connect the power, earth ground, and the type and size of fuses.

5.2.2 Brake Wiring

- Connect the machine brake and emergency brake as shown.
- The brake switches are wired normally closed from HWEC.
- To change the switches to function as normally closed, remove the blue wire from the terminal block in the electrical enclosure, and replace it with the spare gray wire coming from the brake switch.



WARNING

- Brake coils are designed to be de-energized during each elevator stop.
- Verify brake voltage with a meter at the machine.
- 110 VDC excitation voltage for 3 seconds.
- 70 VDC "hold" voltage.

5.3 Brake Adjustment

V WARNING

Before performing any maintenance on the machine brakes, take all necessary safety precautions to immobilize the car and counterweight to prevent any unintended movement during the maintenance period that may result in injury or death!

V WARNING

Brakes must be adjusted after the car and counterweight are suspended by the machine!

As brake pads are worn or new pads are installed readjustment is required.

Read all of section 5.3 prior to adjusting brake!

5.3.1 Required Tools

- TORQUE WRENCH (45 FT-LBS)
- 16MM SOCKET
- 21MM OPEN END WRENCH
- 0.012" (0.30MM) FEELER GUAGE (USED AS GO)
- 0.016" (0.40MM) FEELER GUAGE (USED AS NO-GO)
- 0.022" (0.55MM) FEELER GUAGE (MAX AIR GAP CHECK)

5.3.2 Air gap (See Figure 9 through Figure 12)

The air gap of the brake is the space between the brake body and the moveable shoe plate (shown in Figure 9). This gap must be checked to ensure proper operation of the brake. The correct air gap is between 0.012" (0.30 mm) to 0.022" (0.55 mm). It is preferable to keep the gap close to minimum < 0.016" (0.36 mm).

BULLETIN

GLV-40S1 #1196 GEARLESS TRACTION MACHINE



Figure 9



Figure 10



Figure 11

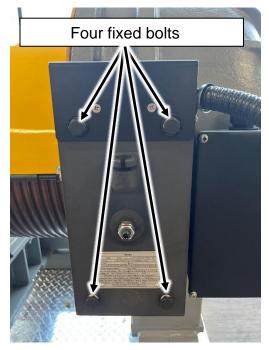


Figure 12

5.3.2.1 Air gap adjustment

An initial air gap check is to take place after the block brake has been properly installed and fixed bolts torqued to 45 ft-lb. (car and counterweight suspended by machine).

- 1. Using a 16 mm wrench, loosen the four fixed bolts. See Figure 10.
- 2. Using a torque wrench and 16 mm socket, torque the fixed bolts in an "X" pattern to 45 ft-lb (60 N-m) See Figure 10.
- 3. Confirm the air gap using a 0.012" (0.30 mm) and 0.016" (0.36 mm) go no-go feeler gauge to check the air gap at all four corners. The 0.012 (0.030 mm) go should feeler gauge should fit and the 0.016" (0.36 mm) should not fit. If this is the case, no adjustment is necessary. See Figure 9.

5.3.2.2 When the air gap of brake is more than 0.016" (0.36 mm), please do as follows:

- 1. Loosen one of the 4 fixed bolts with a 16 mm wrench. See Figure 10.
- Use a 21 mm wrench, rotate the adjustment bolt corresponding to the loosened fixed bolt in small increments, less than ½ a flat of the hex head, counterclockwise. See Figure 11.
- 3. Retorque the 16mm fixed bolts to 45 ft-lbs. (60 N-m) See Figure 10.
- 4. Confirm air gap is 0.012 (0.30mm) to 0.016" (0.36 mm) using a feeler gauge. See Figure 9. Repeat for 3 remaining bolts.

5.3.2.3 When the air gap of brake is less than 0.012" (0.30 mm) please do as follows:

- 1. Loosen one fixed bolt with a 16 mm wrench see Figure 10.
- 2. Turn the 21 mm adjustment bolt corresponding to the loosened fixed bolt clockwise in small increments, less than ½ turn of the hex head flat. See Figure 11.
- 3. Retorque 16 mm fixed bolts to 45 ft-lb (60 N-m). See Figure 10.
- 4. Confirm air gap is within 0.012" (0.30 mm) to 0.016" (0.36 mm) using a feeler gauge. See Figure 9.

5.3.3 Manual Brake Release "Arm Free play"

- Check "free travel" only after 5.3.1 Brake Air Gap has been completed.
- Manual release arm "free travel is factory set to $\frac{1}{2}$ " both directions. See Figure 13.
- Move Brake Arm without handle as shown below, while measuring the travel.
- If Adjustment is needed contact HOLLISTER WHITNEY ELEVATOR.

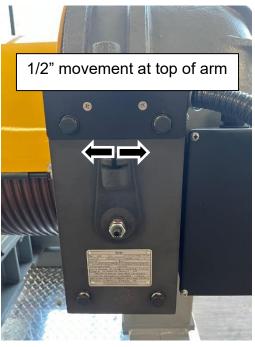


Figure 13

5.3.4 Verify Brake Function

When testing the brakes electrically energize them. Once brakes are adjusted run the car to verify the brakes are relatively quiet on stop and start. Verify no noticeable rubbing noise occurs during machine operation. Once adjustment is confirmed ensure dust guards are present to prevent dust buildup which can cause brake failure.

5.4 Brake Burnishing

V WARNING

Brakes must be burnished to achieve full stopping torque!

Each brake on the machine must be burnished separately. Repeat the following procedure for each brake.

- 1. Clamp the brake on the rotor. Ensure brake circuit is de-energized.
- 2. Run the elevator in the direction of the load at 11 RPM for 1 minute.
 - a. If the overall travel of the elevator will not allow the burnishing time to be met in one pass, open (energize) the brake at the bottom of the hoist way, lift the load back to the top, and repeat the run until the burnishing time is achieved.
 - b. Stop the elevator occasionally to ensure the brake and motor do not overheat.
- 3. After burnishing time is achieved re-verify the air gap between the brake pads and rotor. Ensure air gap is within 0.012" (0.30 mm) to 0.022" (0.55 mm) using a feeler gauge.

5.5 Encoder Connection

The machines are supplied with Heidenhain ECN1313 2048 encoder. A 1.5-meter encoder cable is connected to the encoder and extends from the back of the machine.

Connect the supplied encoder cable to the encoder cable extending from the back of the machine.

When using a KEB drive, the encoder cable can be used "as-is."

When using any other manufacturer's drive, consult control manufacturer for cable compatibility and availability. DO NOT modify the KEB cable without first consulting the control manufacturer. Any modification of the KEB cable voids its warranty.

5.6 Startup

Verify all the motor related settings in the elevator controller match the information on the machine data tag. Refer to Figure 1.

Verify that all the brake parameters match the information on the machine data tag. Refer to Figure 1.

Follow the controller manufacturer's procedure for alignment of the magnets (motor learn).

Briefly run the machine to verify the machine functionality and brake operation.

Verify the drive sheave is plumb and aligned with the rope drop locations.

Install the hoist ropes, adjust the rope shackles, and check the ropes for equal tension. The rope tension must be uniform, or it may cause vibration and premature wear on the traction sheave and hoist ropes.

Re-verify the traction sheave is plumb once the machine is fully loaded.

5.7 Manual Brake Release

The brakes can be manually released in the event of loss of power.

NOTE: The manual releasing device should be operated by 2 professionals, and make sure the power is shut down first.

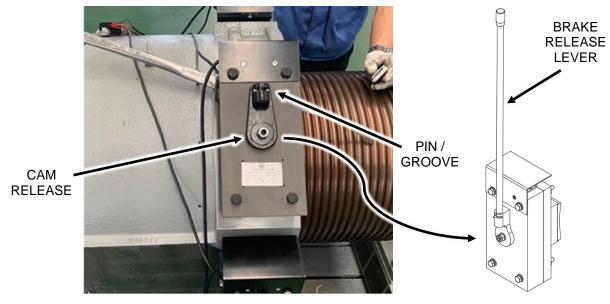


Figure 14

- 1. Insert the brake release lever into the cam release on top of each brake. Align the pin on the brake release lever with the mating groove on the cam release to prevent the brake release lever from slipping.
- 2. Apply force to the end of the brake release lever until the brake releases from the brake wheel.
- 3. The brake release levers must be removed from the cam release prior to normal elevator operation.



6 Maintenance

9 WARNING

Before performing any maintenance checks on equipment, take all the necessary safety precautions to immobilize the car and counterweight to prevent any unintended movement during the maintenance period that may result in injury or death!

6.1 General

To keep equipment functioning efficiently, good maintenance practices must be established, observed, and maintained. Systematic inspections of the equipment should be scheduled, and records kept of these inspections. Monitoring these records will indicate any sign of a potential issue.

Each installation has its own special conditions, so it is not possible for HWEC to outline an overall plan for periodic maintenance. HWEC would recommend, at a minimum, yearly inspections, but installation conditions may warrant a more frequent schedule. The maintenance contractor will need to make the final determination.

6.2 Cleaning

Dirt, dust, excess lubrication, and moisture are the greatest enemies of electrical equipment and of maintenance teams in general. Dirt and dust layers on a machine can prevent heat dissipation, which can lead to overheating and eventual insulation breakdown. Many types of dust in an elevator machine room are electrically conductive and can also lead to insulation failure. Dust and dirt can draw moisture to unpainted surfaces such as brake rods causing oxidation that can cause brake faults. Excess lubrication can draw dust and dirt as well.

Dust and dirt can be removed from surfaces with a dry, lint-free cloth, or with suction. With suction, however, care must be taken to not build up or discharge static electricity while cleaning. Dry, compressed air (at less than 50psi) may also be used to remove dirt and dust, however, this must be closely monitored as the compressed air will re-suspend the dust and dirt in the machine room atmosphere.

6.3 Bearings

POINTS

Bearings have been sized for the maximum speeds, loads and capacities found in this manual at 50% duty. Bearings must be greased at least yearly, but greasing frequency will depend on duty and hoistway conditions.

1. To grease bearings, first remove the pressure relief plugs from the outboard stand and the back of the machine. See Figure 15.

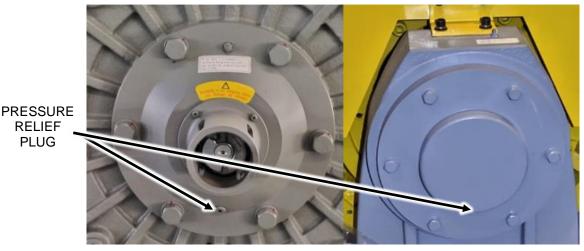


Figure 15

2. The grease point is opposite the relief plug. Figure 16.



Figure 16

3. Apply 2-3 oz. of grease (use Shell "Gadus S3 V220C 2" or equal) at least yearly or according to the maintenance schedule for the installation conditions.

Bearings calculated life rating (based on speed, loads and 50% duty) is approximately 20 years. Please note that installation conditions vary, so shorter or longer bearing life may be experienced.

6.4 Brake Wear

V WARNING

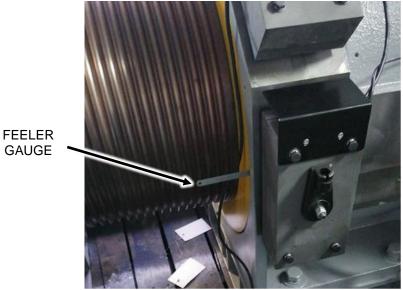
If the brake pad wears too much, the brake will be disabled.

6.4.1 Suggested check cycle

- Every 3 months after install in the first 6 months.
- Every 1 year afterwards.

6.4.2 Benchmark Criteria

- Check the brake for flexibility, the brake pad and traction sheave for wear, and the bearings. Replace worn and damaged parts when necessary.
- As the brake pad wears it adds to the air gap and could contribute to braking noise. You may adjust the air gap as detailed in Section 0.
- If brake pad wear is excessive replace the brake pad or replace the entire brake assembly. See Figure 17.



GAUGE

Figure 17

6.5 Other Items

The traction wheel, brake shoe, and brake wheel are usually the only components that will wear. Among them, the brake wheel is most unlikely to wear. Brake pads are more likely to wear but can be monitored with feeler gauges. Refer to the brake section of this manual for brake inspection procedures.

The winding working temperature of traction machine shall not exceed 130 °C. It can be controlled by the thermal switch in the main machine. When the temperature reaches 130 °C, the traction machine shall be stopped.

When the traction machine rotates under the passive condition, it will be in the state of power generation. At this time, high voltage will be generated at the host terminal. Attention shall be paid to avoid electric shock and equipment damage.

Grease and other impurities shall be avoided between the brake pad and the brake wheel to avoid the decrease of braking force of the brake system. If the residual thickness of the brake pad is less than 5 mm due to wear, the brake pad shall be replaced.

Traction wheels are the most likely item on the machines to wear. Periodic measurements of rope depth and the evenness of wear for all ropes (groove depth should wear evenly) should be monitored. Cable should not be more than 0.125 inch (1/8") below the outer rim of the traction wheel. If cable(s), are below 0.125 inch, or if wear is uneven, replace the traction wheel and cables.

Check machine guarding and rope retainers for clearance and attachment hardware for tightness. Adjust as necessary.



7 Replacement

V WARNING

Have only qualified personnel perform the replacement work. The person who performs the replacement work must make sure that the machine power is off, and that the elevator will not move unexpectedly.

7.1 Encoder Replacement

Required Tools & Materials:

- Encoder (ECN1313)
- Hex wrench
 - \circ 2 mm
 - \circ 4 mm
 - \circ 6 mm
 - o **8 mm**
- Hex sockets
 - o 2 mm
 - o **4 mm**
- Torque Wrench (Need to measure 9 in-lbs. and 44 in-lbs.)
- M10 bolt (at least 1" or 25 mm in length)

7.1.1 Encoder Removal

The encoder can be removed from the front of the machine. See Figure 18.

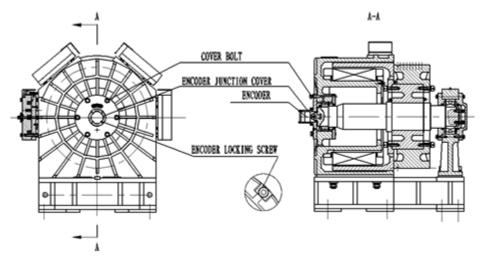


Figure 18

1. Loosen the encoder locking screw M2.5, as shown in Figure 19 with hex wrench (2 mm) through the encoder cover hole. The screw does not need to be removed.

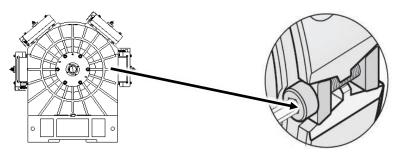


Figure 19

2. Remove the encoder bolt cover using the hex wrench (4 mm) and the encoder cable protective cover. See Figure 20.



Figure 20

3. Carefully remove wiring harness connector, See Loosen the bolt M5 inside by hex wrench (4 mm) 2~3 turns only. Do not remove this bolt.

(M5 bolt must remain in the encoder so the M10 bolt can push against it). See Figure 22.

- 4. Insert a M10 bolt into the encoder housing. See Figure 23.
- 5. Leave the encoder cable on the machine. It does not need to be removed.

Note: Do not apply excessive pressure on the cable. It may destroy the encoder cable.



Figure 21

6. Loosen the bolt M5 inside by hex wrench (4 mm) 2~3 turns only. Do not remove this bolt.

(M5 bolt must remain in the encoder so the M10 bolt can push against it). See Figure 22.



Figure 22

7. Insert a M10 bolt into the encoder housing. See Figure 23.



Figure 23

8. Turn the M10 bolt against the M5x50 bolt to push the encoder from the shaft. The encoder will "pop" free and will be loose to the touch yet still retained by the M5 bolt. See Figure 24.



Figure 24

9. Remove both bolts and the encoder, See Figure 25.



Figure 25

7.1.2 Encoder Installation

What's in the box. See Figure 26.



Figure 26

1. Loosen and remove the bolt M2.5 and nut assembly in the new encoder. See Figure 27.



Figure 27

2. There is a taper in the front of the encoder shaft, put the encoder shaft into the hole of the shaft. Figure 28.

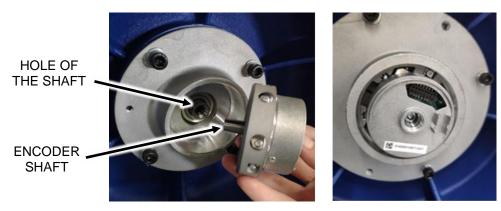


Figure 28

3. Install the encoder. Use the bolt M5 to secure the encoder to the encoder cover by hex wrench (4mm). Use 4mm socket Allen and torque wrench to tighten the bolt to 44 in-lbs. See Figure 29.



Figure 29

4. Rotate the encoder, it should be very flexible at this time, tighten the encoder locking screw according to 11 in-lbs. by a hex wrench so the encoder outer cannot rotate by hand. See Figure 30.



Figure 30

5. Install the encoder cable on the encoder. Take care to orient the plug and socket correctly. See Figure 31.



Figure 31

Page 7-6 Rev. E – 04/10/2024 6. Place the cable cover on the encoder and secure with the encoder cover bolt (and cover) to the encoder. See Figure 32.



Figure 32

- 7. Reconnect the power supply of machine and test it.
- 8. Align the encoder per controller instructions.

7.2 Brake Replacement

Required Tools & Materials:

- Adjustable wrench
- Hex wrench (4 mm, 5 mm)
- Small flat head screwdriver



Before performing any maintenance on the machine brake(s), secure the counterweight and take all the necessary safety precautions to immobilize the car and counterweight to prevent any unintended movement during the maintenance period that may result in injury or death!

Read the entire brake replacement procedure before beginning any of the steps outlined below. Contact HWEC with any questions prior to beginning the brake repair or replacement.

Before opening any electrical enclosures on the machine, remove all electricity from the machine and brakes to prevent electrical shock that may result in injury or death during the maintenance period!

7.2.1 Brake Removal

- 1. Remove covers as necessary to access terminal blocks and brake pin set screw (4mm hex key).
- 2. Disconnect machine power, see Figure 33.

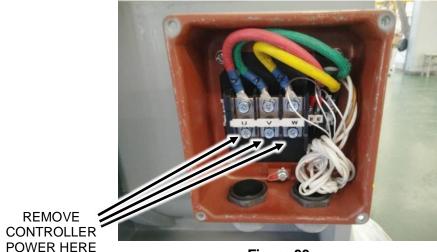


Figure 33

3. On the machine side disconnect the Brake and Brake Switch wires for the brake that is to be worked on, see Figure 34.

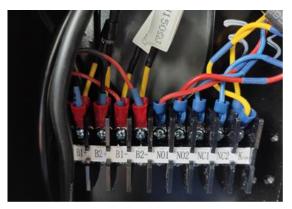
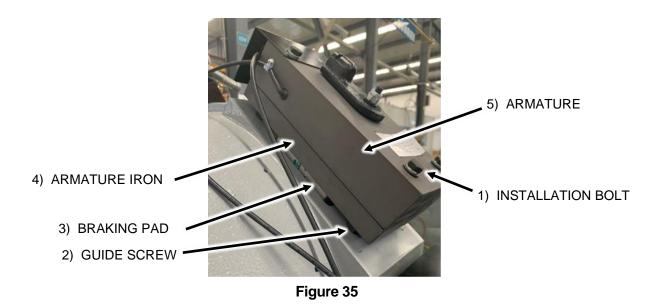


Figure 34

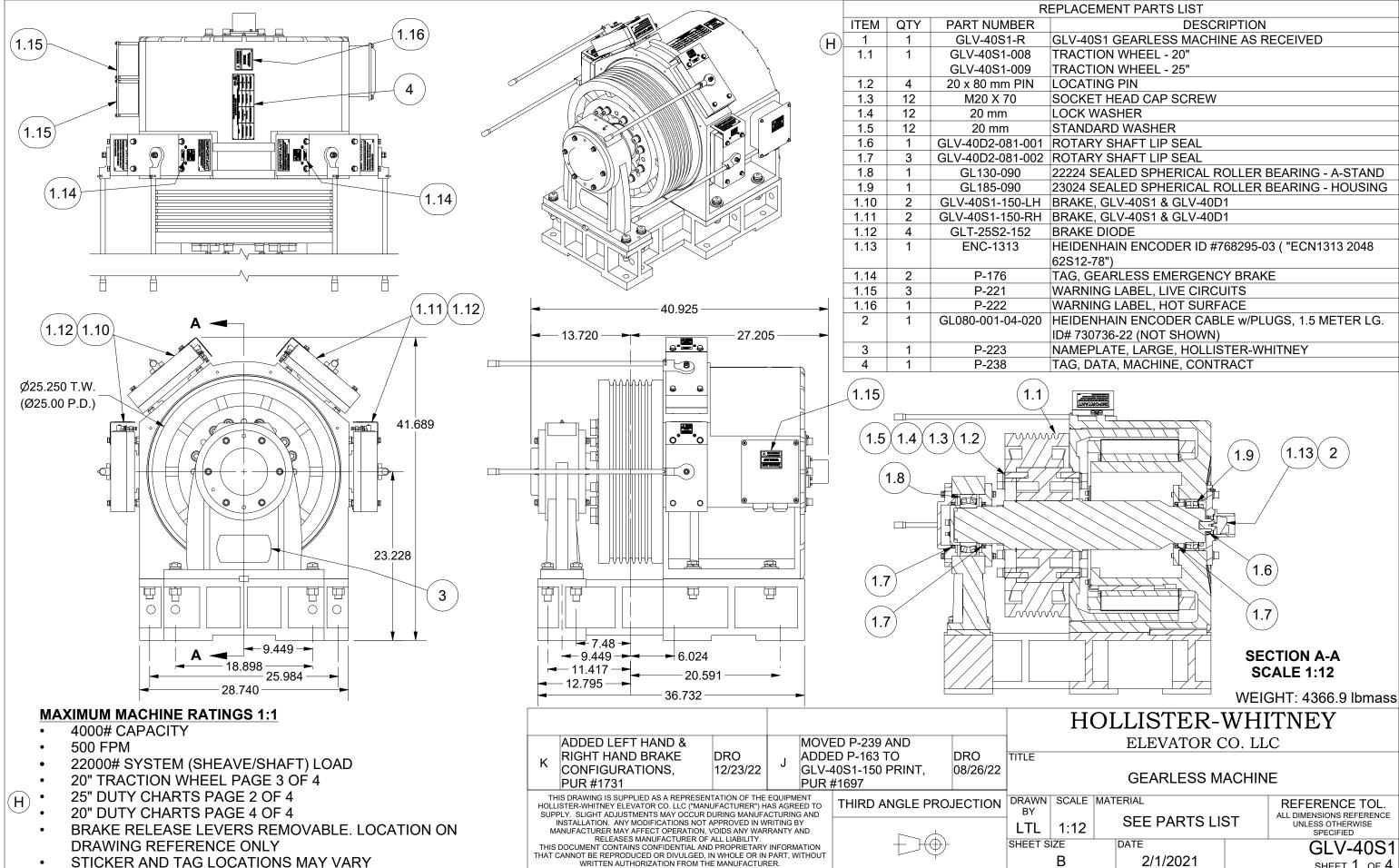
- 4. Use a wrench to loosen the mounting bolt of the installation bolt 1, so that the end face of the guide screw sleeve of the guide screw 2 is separated from the mounting surface of the base.
- 5. Remove the brake and related connecting accessories.
- 6. New or repaired brakes are replaced in the reverse order of the above instructions.

7. Adjust the guide screw sleeve of guide screw 2 and the mounting bolt of insulation bolt 1, so that the air gap between the armature of armature 5 and the armature of armature iron 4 is between 0.012" (0.30 mm) to 0.022" (0.55 mm), the gap between the brake belt and the brake wheel is 0.004" (0.10 mm) to 0.006" (0.15 mm), and the distance between the guide screw sleeve of guide screw 2 and the iron surface of armature iron 4 is about 0.197" (5 mm). no less than 0.118" (3 mm) under any conditions, as shown in Figure 35.



7.2.2 Brake Adjustment

After installation of the brake, please refer to Section 5.3 to confirm brake is centered and air gap has been restored to factory specifications.



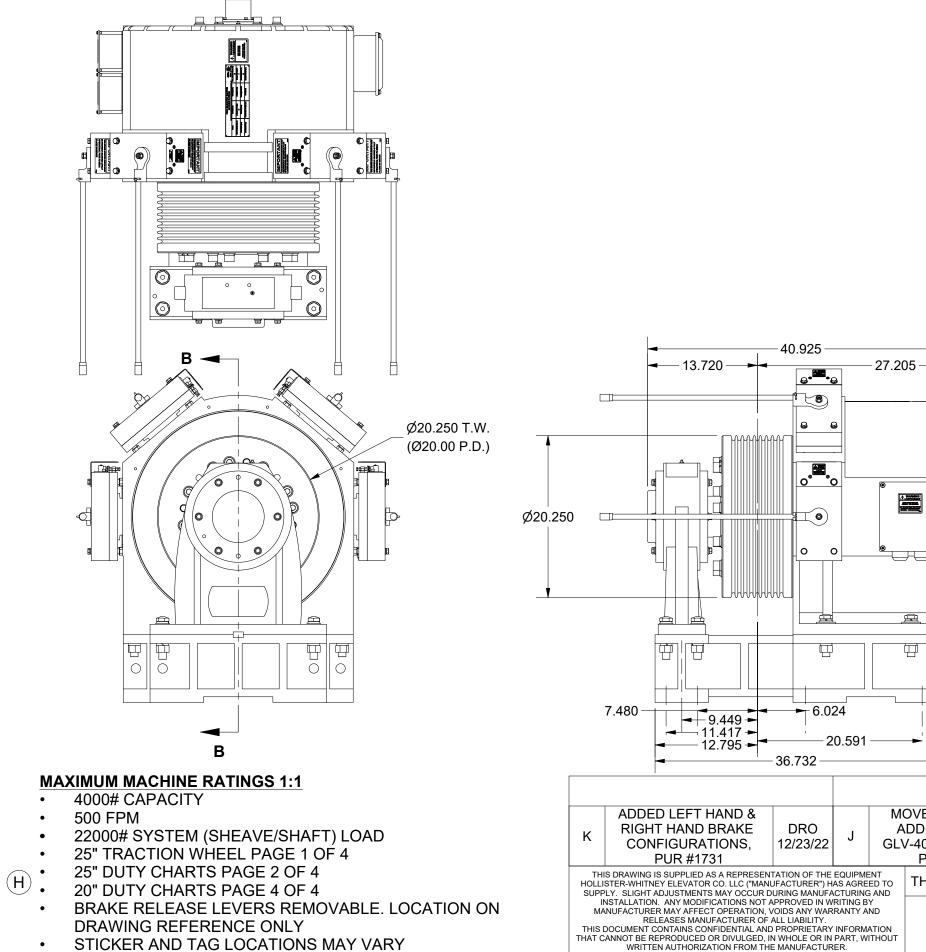
REPLACEMENT PARTS LIST
DESCRIPTION
GLV-40S1 GEARLESS MACHINE AS RECEIVED
TRACTION WHEEL - 20"
TRACTION WHEEL - 25"
LOCATING PIN
SOCKET HEAD CAP SCREW
LOCK WASHER
STANDARD WASHER
ROTARY SHAFT LIP SEAL
ROTARY SHAFT LIP SEAL
22224 SEALED SPHERICAL ROLLER BEARING - A-STAND
23024 SEALED SPHERICAL ROLLER BEARING - HOUSING
BRAKE, GLV-40S1 & GLV-40D1
BRAKE, GLV-40S1 & GLV-40D1
BRAKE DIODE
HEIDENHAIN ENCODER ID #768295-03 ("ECN1313 2048
62S12-78")
TAG, GEARLESS EMERGENCY BRAKE
WARNING LABEL, LIVE CIRCUITS
WARNING LABEL, HOT SURFACE
HEIDENHAIN ENCODER CABLE w/PLUGS, 1.5 METER LG.
ID# 730736-22 (NOT SHOWN)
NAMEPLATE, LARGE, HOLLISTER-WHITNEY
TAG, DATA, MACHINE, CONTRACT

	SCALE	MATERIAL		REFERENCE TOL.
	1:12	SEE PARTS LIS	ST	ALL DIMENSIONS REFERENCE UNLESS OTHERWISE SPECIFIED
S	IZE	DATE		GLV-40S1
	В	2/1/2021		SHEET 1 OF 4

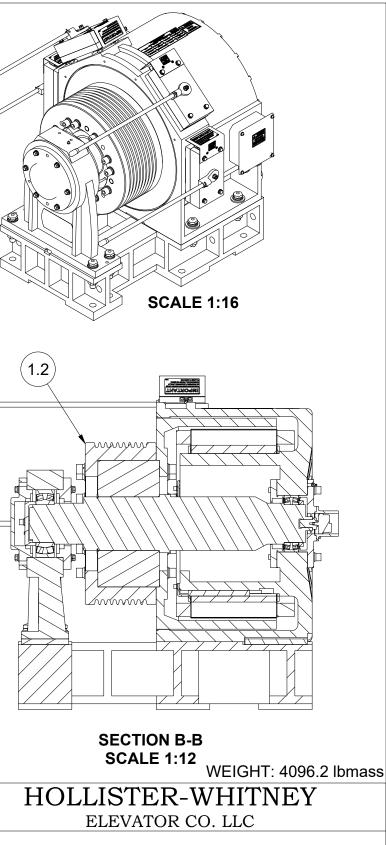
HW Ordering Part #	Supplier Part #	Capacity	Speed	Motor	Motor	Poles	Rated	Rated	Actual	Rated	Rated	Peak	Estimated	Max	Estimated	Rated	MaxAccel	Cwt(%)	Sheave	Motor Winding	Brake Information	Rope/Groove
		(lbs)	(fpm) 100	Rating (HP) 5.1	Rating (kW) 3.8	30	(rpm) 15.3	Voltage 380	Voltage 156.0	Freq(Hz) 3.9	Current(A) 16.7	Current (A) 40.1	Efficiency 80.6%	BTU/hr 2531	BTU/hr 810	Torque(ft-lbs) 1764	Torque(ft-lbs) 3528	50	Dia(") 25	Specification		Information
		2500	150	7.7	5.7	30	22.9	380	234.0	5.8	16.7	40.1	85.2%	2903	929	1764	3528	50	25			
			200	10.3	7.7	30	30.6	380	312.0	7.7	16.7	40.1	87.6%	3244	1038	1764	3528	50	25			
			100	6.0	4.4	30	15.3	380	158.2	3.9	19.3	46.3	78.2%	3328	1065	2048	4096	50	25			Grooves to be
		3000	150 200	8.9 11.9	6.6 8.8	30 30	22.9 30.6	380 380	26.2 316.0	5.8 7.7	19.3 19.3	46.3	84.0% 86.3%	3623 4148	1159 1327	2048	4096 4096	50 50	25 25			machined at
GLV-40S1-C-VS401B	WYT-V1S-1.0EFS635-VS401B		100	7.1	5.3	30	15.3	380	159.5	3.9	23	55.2	76.2%	4148	1366	2048	4098	50	25	WYT-V1S.1.1-VS401B		Bluelight
		3500	150	10.6	7.9	30	22.9	380	239.3	5.8	23	55.2	82.1%	4818	1542	2428	4856	50	25			_
			200	14.1	10.5	30	30.6	380	319.0	7.7	23	55.2	85.4%	5261	1684	2428	4856	50	25			Standard Groovin
		4000	100	7.9	5.9	30	15.3	380	165.5	3.9	25.8	61.9	74.4%	5168	1654	2731	5462	50	25			9 - 5/8" grooves on
		4000	150 200	11.9 15.9	8.9 11.8	30 30	22.9 30.6	380 380	248.3 331.0	5.8 7.7	25.8 25.8	61.9 61.9	80.8% 84.3%	5825 6331	1864 2026	2731 2731	5462 5462	50 50	25 25			pitch
			250	12.8	9.6	30	38.2	380	211.4	9.6	28.6	68.6	88.7%	3691	1181	1764	3528	50	25			using the followir
		2500	300	15.4	11.5	30	45.8	380	253.7	11.6	28.6	68.6	89.5%	4101	1312	1764	3528	50	25		Brake Part Number:	groove profile:
			350	18.0	13.4	30	53.5	380	296.0	13.5	28.6	68.6	90.1%	4507	1442	1764	3528	50	25		D1D 110RB	
		3000	250 300	14.9 17.8	11.1 13.3	30	38.2 45.8	380	212.3 255.4	9.6	33 33	79.2 79.2	88.1% 89.2%	4512 4891	1444 1565	2048	4096 4096	50 50	25 25		Brake Ob/	
		3000	300	20.8	13.3	30 30	45.8 53.5	380 380	255.4	11.6 13.5	33	79.2	89.2%	4891 5451	1744	2048	4096	50	25		<u>Brake Qty</u> : 4	
GLV-40S1-C-VS402B	WYT-V1S-1.75EFS635 -VS402B		250	17.7	13.2	30	38.2	380	214.3	9.6	39.3	94.3	87.3%	5696	1823	2428	4856	50	25	WYT-V1S.1.1-VS402B	Pick Volts, Amps:	See Grooving Prir
		3500	300	21.2	15.8	30	45.8	380	257.1	11.6	39.3	94.3	88.6%	6150	1968	2428	4856	50	25		110, 1.98	GRVH-TVU-0450
			350	24.7	18.4	30	53.5	380	300.0	13.5	39.3	94.3	89.5%	6590	2109	2428	4856	50	25		Hold Volts, Amps:	Standard 5/8" Gro
		4000	250 300	19.9 23.8	14.8 17.8	30 30	38.2 45.8	380 380	221.4 265.7	9.6 11.6	44.2 44.2	106.1 106.1	86.6% 88.0%	6797 7279	2175 2329	2731 2731	5462 5462	50 50	25 25		70, 1.26	Profile
		4000	350	27.8	20.7	30	53.5	380	310.0	13.5	44.2	106.1	89.1%	7740	2477	2731	5462	50	25			
			400	20.5	15.3	30	61.1	380	232.8	15.2	41.4	99.4	90.5%	4938	1580	1764	3528	50	25			
		2500	450	23.1	17.2	30	68.8	380	261.9	17.1	41.4	99.4	90.9%	5367	1718	1764	3528	50	25			
			500 400	25.7 23.8	19.1 17.8	30 30	76.4 61.1	380 380	291.0 233.5	19.0 15.2	41.4 48	99.4 115.2	91.1% 90.3%	5809 5874	1859 1880	1764 2048	3528 4096	50 50	25			
		300 450 26.9 20.0 30 68.8 380 262.3 17.1 48 115.2 90.6% 6434 2059	2048	4096	50	25 25																
			500	29.9	22.2	30	76.4	380	292.0	19.0	48	115.2	91.3%	6619	2118	2048	4096	50	25			
GLV-40S1-C-VS403B	WYT-V1S-2.5EFS635-VS403B		400	28.3	21.1	30	61.1	380	234.4	15.2	57	136.8	90.1%	7102	2273	2428	4856	50	25	WYT-V1S.1.1-VS403B		
		3500	450	31.8	23.7	30	68.8	380	263.7	17.1	57	136.8	90.7%	7556	2418	2428	4856	50	25			
			500 400	35.3 31.8	26.3 23.7	30 30	76.4 61.1	380 380	293.0 238.4	19.0 15.2	57 64	136.8 153.6	91.1% 89.8%	8018 8277	2566 2648	2428 2731	4856 5462	50 50	25 25			
		4000	450	35.8	26.7	30	68.8	380	268.2	17.1	64	153.6	90.4%	8744	2798	2731	5462	50	25			
			500	39.7	29.6	30	76.4	380	298.0	19.0	64	153.6	90.9%	9218	2950	2731	5462	50	25			
(F	I)	H																				
																						WEIG
NOTES UNI 1. BRAKE	ESS OTHERWISE S		IED:																HC	DLLISTEI	-WHIT	`NEY

- DE-ENERGIZED 2. BRAKE INFORMATION:
- PICK VOLTS: 110 •
- PICK AMPS: 1.98 •
- HOLD VOLTS: 70 •
- HOLD AMPS: 1.26 •

				5.44			_	HC	DLLISTER-V		
к	ADDED LEFT HAND & RIGHT HAND BRAKE CONFIGURATIONS,	A	OVED P-239 AND \DDED P-163 TO /-40S1-150 PRINT,	DRO 08/26/22	TITLE		ELEVATOR C				
	PUR #1731				PUR #1697 THIRD ANGLE PRO	JECTION		CALE M	GEARLESS MA		E REFERENCE TOL.
SUPF	HOLLISTER-WHITNEY ELEVATOR CO. LLC ("MANUFACTURER") HAS AGREED TO SUPPLY. SLIGHT ADJUSTMENTS MAY OCCUR DURING MANUFACTURING AND INSTALLATION. ANY MODIFICATIONS NOT APPROVED IN WRITING BY MANUFACTURER MAY AFFECT OPERATION, VOIDS ANY WARRANTY AND RELEASES MANUFACTURER OF ALL LIABILITY.					LTL		SEE PARTS LIS	ST	ALL DIMENSIONS REFERENCE UNLESS OTHERWISE SPECIFIED	
	DOCUMENT CONTAINS CONFIDENTIAL AND ANNOT BE REPRODUCED OR DIVULGED, I WRITTEN AUTHORIZATION FROM TH	O PROPRIETARY N WHOLE OR IN	PART, W				SHEET SIZE	е З	DATE 2/1/2021		GLV-40S1 SHEET 2 OF 4



MOVED P-239 AND ADDED P-163 TO GLV-40S1-150 PRINT, PUR #1697 THIRD ANGLE PROJECTION ND ON ON ON THIRD ANGLE PROJECTION BY LTL SHEET SI



GEARLESS MACHINE

	SCALE	MATERIAL		REFERENCE TOL.
	1:12	SEE PARTS LIS	ST	ALL DIMENSIONS REFERENCE UNLESS OTHERWISE SPECIFIED
5	IZE	DATE		GLV-40S1
	В	2/1/2021		SHEET 3 OF 4

Wind dering Part 1 Supplie Part 1 Sup			Capacity	Speed	Motor	Motor		Rated	Rated	Actual	Rated	Rated	Peak	Estimated	Max	Estimated	Rated	MaxAccel		Sheave	Motor Winding		Rope/Groove	
No. 0 No. 0 S.1 3.8 S.0 S.0 V.2 V.1 V.	HW Ordering Part #	Supplier Part #	. ,	(fpm)			Poles	(rpm)	Voltage	Voltage	Freg(Hz)	Current(A)	Current (A)	Efficiency	BTU/hr	BTU/hr	Torque(ft-lbs)	Torque(ft-lbs)	Cwt(%)		Specification	Brake Information	Information	
No. 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1			, ,		e ,	3.8	30	· · · ·				17.1		,			1409	2818	50		•			
Number of the series of the serie			2500									-	41.0		-	+ +			_					
 <td></td> <td></td> <td></td> <td>200</td> <td>10.2</td> <td>7.6</td> <td>30</td> <td>38.2</td> <td>380</td> <td>312.0</td> <td>9.5</td> <td>17.1</td> <td>41.0</td> <td>88.4%</td> <td>3020</td> <td>966</td> <td>1409</td> <td>2818</td> <td>50</td> <td>20</td> <td></td> <td></td> <td></td>				200	10.2	7.6	30	38.2	380	312.0	9.5	17.1	41.0	88.4%	3020	966	1409	2818	50	20				
NULL				100	6.0	4.4	30	19.1	380	158.0	4.8	19.9	47.8	81.4%	2840	909	1639	3278	50	20				
NAMESI C YADA MPT-VIS-LIDESOR SHAPE IO 7.1 5.3 0.0 7.1 5.3 0.0 7.1 5.3 0.0 7.1 5.3 0.0 7.0 2.0 7.0 2.00 7.0 2.00 7.0 2.00 7.0 2.00 7.0 3.00 2.00 7.0 3.00 2.00 7.0 3.00 2.00 7.0 3.00 2.00 7.0 3.00 2.00 7.0 3.00 2.00 7.0 3.00 2.00 7.0 3.00 9.00 7.00 <th< td=""><td></td><td></td><td>3000</td><td>150</td><td>8.9</td><td>6.7</td><td>30</td><td>28.6</td><td>380</td><td>236.3</td><td>7.2</td><td>19.9</td><td>47.8</td><td>85.7%</td><td>3238</td><td>1036</td><td>1639</td><td>3278</td><td>50</td><td>20</td><td></td><td></td><td>Concernante la</td></th<>			3000	150	8.9	6.7	30	28.6	380	236.3	7.2	19.9	47.8	85.7%	3238	1036	1639	3278	50	20			Concernante la	
N 100 7.1 5.3 30 19.0 19.5 48 23.6 23.6 56.6 8.7.2 19.91 1984 3882 50 20 100 10.0				200	11.9	8.9	30	38.2	380	315.4	9.5	19.9	47.8	87.2%	3876	1240	1639	3278	50	20	W/YT V/15 1 1 V/S/01A	Grooves to be		
$ \left. \begin{array}{ c c c c c c c c c c c c c c c c c c c$	3LV-4031-C-V3401A	WYT-V15-1.0EF5508-V5401A		100	7.1	5.3	30	19.1	380	159.5	4.8	23.6	56.6	79.2%	3742	1197	1941	3882	50	20	WY1-V15.1.1-V5401A		machined at	
her 100 7.9 7.9 9.0 <td></td> <td></td> <td>3500</td> <td>150</td> <td>10.6</td> <td>7.9</td> <td>30</td> <td>28.6</td> <td>380</td> <td>239.3</td> <td>7.2</td> <td>23.6</td> <td>56.6</td> <td>84.2%</td> <td>4261</td> <td>1363</td> <td>1941</td> <td>3882</td> <td>50</td> <td>20</td> <td></td> <td rowspan="2"></td> <td>Bluelight</td>			3500	150	10.6	7.9	30	28.6	380	239.3	7.2	23.6	56.6	84.2%	4261	1363	1941	3882	50	20			Bluelight	
Image: Probability of the series of				200	14.1	10.5	30	38.2	380	319.0	9.5	23.6	56.6	86.9%	4718	1510	1941	3882	50	20			Standard Groovin	
Image weight we				100	7.9	5.9	30	19.1	380	165.5	4.8	26.5	63.6	77.6%	4527	1449	2185	4370	50	20				
New Press No. 1.0. 1.0. 3.0. 3.0. 3.0. 3.0. 3.0. 7.0.5 63.0. 68.18 69.0.8 1.0.0 2.105 4.3.0. 2.0. 1.0. 3.0. 2.0. 1.0.0 2.0.0<			4000	150	11.9	8.9	30		380	248.3	7.2	26.5	63.6	83.1%		1640	2185	4370	50	20			10 - 1/2" groove	
64.0 500 50.0 50.1				200	15.9	11.9	30	38.2	380	331.0	9.5	26.5	63.6	86.1%	5628	1801	2185	4370	50	20			3/4" pitch	
No. 1000 1000 101 100 101 100 100 100 1000 1				250			30				1		72.7	91.3%	2844			2818	50				• •	
NUME <			2500	300	15.4	11.5	30		380		14.4	30.3	72.7	92.2%			1409	2818	50	20		Brake Part Number:	using the follow	
$ \left. \begin{array}{cccccccccccccccccccccccccccccccccccc$				350	17.9	13.4	30	66.8	380		16.8	30.3	72.7	92.9%	3242	1038	1409	2818	50	20		D1D 110RB	groove profile	
NVT-V151-75EF5508-V5402A Image: Field of the state stat				250	14.8	11.1	30		380		12.0	35.3	84.7	90.5%				3278	50	20				
SUV-4051-CV5402A WYT-V15.175EFS508-V5402A 250 17.6 13.2 30 47.7 380 21.4.3 12.0 41.8 100.3 89.4% 4752 1521 1941 3882 50 20 300 21.2 15.8 30 57.3 380 257.1 14.4 41.8 100.3 90.7% 4888 1566 1941 3882 50 20 10 300 21.2 15.8 30 57.7 380 257.1 14.4 18.8 100.3 90.7% 4888 1566 1941 3882 50 20 00 02.8 17.8 30 57.7 380 221.4 12.0 47.7 13.8 90.7% 488 1365 2185 4370 50 20 000 23.8 17.8 30 7.7 380 221.8 10.1 380 218 50 218 50 20 000 25.6 19.1 <t< td=""><td></td><td></td><td>3000</td><td>-</td><td></td><td></td><td>-</td><td></td><td></td><td>1</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td rowspan="2">20 WYT-V1S 1 1-V</td><td></td><td rowspan="2">4</td><td></td></t<>			3000	-			-			1										20 WYT-V1S 1 1-V		4		
$ \left. \begin{array}{c c c c c c c c c c c c c c c c c c c $	GLV-40S1-C-VS402A	WYT-V1S-1.75EES508 -VS402A		_											-						WYT-V1S.1.1-VS402A			
$ \left(\begin{array}{c c c c c c c c c c c c c c c c c c c $																			-					
Best of the second se			3500																		_	_	· · ·	с с · р
4000 300 23.8 17.8 30 57.3 380 265.7 14.4 47 112.8 90.% 6051 1936 2185 4370 50 20 350 27.8 20.7 30 66.8 380 310.0 16.8 47 112.8 91.% 6298 2015 2185 4370 50 20 400 20.5 21.3.1 30.7 66.8 380 21.8 40.9 21.85 41.09 28.18 50 20 500 22.1 17.7 30 85.9 380 261.9 21.4 40.9 98.2 91.% 500 164 10.9 28.18 50 20 500 25.6 19.1 30 76.4 380 23.5 19.0 47.6 114.2 90.% 55.1 1783 1639 327.8 50 20 60.7 29.8 22.9 30 76.4 380 76.4 114.																							See Grooving Pr	
Image: bire state 350 27.8 20.7 30 66.8 380 310.0 16.8 47 112.8 91.1% 6298 2015 2185 4370 50 20 V 10 10 20.5 15.3 30 76.4 380 23.8 19.0 40.9 98.2 90.9% 4750 1520 1409 2818 50 20 400 20.1 17.2 30 85.9 380 261.9 21.4 40.9 98.2 91.9% 560 164 1409 2818 50 20 500 25.6 19.1 30 76.4 380 21.0 21.8 5664 1812 1409 2378 50 20 3000 450 26.8 20.0 30 85.9 380 22.2 21.8 47.6 114.2 91.3% 5664 1812 1639 32.78 50 20 400 28.8 20.0 3.8				-							-				-							70, 1.26	GRVH-TVU-0450	
$ \left(V + 0 $			4000	-																			Standard 1/2" Gro	
$ \left\{ \begin{array}{cccccccccccccccccccccccccccccccccccc$				-																			Profile	
6U-4051-C-V5403A 6U-500 5			2500																					
MAND MAD CAS SAS SAS <td></td> <td></td> <td>2500</td> <td></td>			2500																					
AND 450 26.8 20.0 30 85.9 380 26.2 21.4 47.6 114.2 91.3% 593 1898 1639 3278 50 20 500 29.8 22.2 30 95.5 380 29.2 23.8 47.6 114.2 91.3% 650 1639 3278 50 20 500 29.8 20.2 30 95.5 380 29.2 23.8 47.6 114.2 91.4% 6521 2087 1639 3278 50 20 300 28.2 21.1 30 76.4 380 23.4 19.0 56.4 135.4 90.7% 6667 2133 1941 382 50 20 3500 450 31.8 23.7 30 85.9 380 263.7 21.4 56.4 135.4 91.5% 761 2438 1941 3882 50 20 500 35.3 26.3 26.3<																								
GU-4051-C-V5403A MYT-V15-2.5FF5508-V5403A M 29.8 29.2 3.80 29.2 2.3.8 47.6 114.2 91.4% 65.1 2.087 16.39 3.278 5.0 2.0 400 28.2 21.1 30 76.4 380 23.4 19.0 56.4 135.4 90.7% 6667 21.33 1941 3882 50 20 400 28.2 21.1 30 76.4 380 23.4 19.0 56.4 135.4 90.7% 6667 21.33 1941 3882 50 20 400 31.8 23.7 30 85.9 380 26.37 21.4 56.4 135.4 91.5% 7137 2284 1941 3882 50 20 500 35.3 26.3 30 95.5 380 23.8 56.4 135.4 91.5% 7619 2438 1941 3820 50 20 400 31.8 23.7 30<			2000	-				1											-					
GU-40S1-C-VS403A WYT-V15-2.5EFS508-VS403A 400 28.2 21.1 30 76.4 380 23.4 19.0 56.4 135.4 90.7% 6667 2133 1941 3882 50 20 3500 450 31.8 23.7 30 85.9 380 26.3 21.4 56.4 135.4 90.7% 6667 2133 1941 3882 50 20 400 31.8 23.7 30 85.9 380 26.3 21.4 56.4 135.4 91.5% 7137 2284 1941 3882 50 20 500 35.3 26.3 30 95.5 380 23.8 56.4 135.4 91.5% 7619 2438 1941 3882 50 20 400 31.8 23.7 30 76.4 380 23.8 56.4 135.4 91.5% 7619 2438 1941 3882 50 20 400 31.8			3000																					
3500 450 31.8 23.7 30 85.9 380 263.7 21.4 56.4 135.4 91.2% 7137 2284 1941 3882 50 20 500 35.3 26.3 30 95.5 380 293.0 23.8 56.4 135.4 91.2% 7137 2284 1941 3882 50 20 400 31.8 23.7 30 76.4 380 23.8 19.0 63.5 152.4 90.4% 7730 2474 2185 4370 50 20	GLV-40S1-C-VS403A	WYT-V1S-2.5EFS508-VS403A		_															-		WYT-V1S.1.1-VS403A			
500 35.3 26.3 30 95.5 380 293.0 23.8 56.4 135.4 91.5% 7619 2438 1941 3882 50 20 400 31.8 23.7 30 76.4 380 238.4 19.0 63.5 152.4 90.4% 7730 2474 2185 4370 50 20			3500																					
400 31.8 23.7 30 76.4 380 238.4 19.0 63.5 152.4 90.4% 7730 2474 2185 4370 50 20			3300																					
			4000								-				-	+ +								
500 39.7 29.6 30 95.5 380 298.0 23.8 63.5 152.4 91.4% 8703 2785 2185 4370 50 20		40	4000	-															-					

NOTES UNLESS OTHERWISE SPECIFIED:

- 1. BRAKE SWITCH NORMALLY CLOSED WHEN BRAKE IS DE-ENERGIZED
- 2. BRAKE INFORMATION:
- PICK VOLTS: 110 •
- PICK AMPS: 1.98 ٠
- HOLD VOLTS: 70 •
- HOLD AMPS: 1.26 •

							HOLLISTER-WHITNEY					
	ADDED LEFT HAND &				OVED P-239 AND				ELEVATOR C	O. LL	C	
К	RIGHT HAND BRAKE CONFIGURATIONS, PUR #1731	DRO 12/23/22	J		DDED P-163 TO /-40S1-150 PRINT, 	DRO 08/26/22	TITLE		GEARLESS M/	ACHIN	E	
HOL	HIS DRAWING IS SUPPLIED AS A REPRESEN LISTER-WHITNEY ELEVATOR CO. LLC ("MAN 'PLY. SLIGHT ADJUSTMENTS MAY OCCUR IN INSTALLATION. ANY MODIFICATIONS NOT IANUFACTURER MAY AFFECT OPERATION, DELEFORT MANY ACTURED OF	UFACTURER") HA DURING MANUFA APPROVED IN W VOIDS ANY WAR	AS AGREI CTURING RITING B	ED TO S AND Y		JECTION	DRAWN SC BY LTL	CALE MAT	ERIAL SEE PARTS LIS	ST	REFERENCE TOL. ALL DIMENSIONS REFERENCE UNLESS OTHERWISE SPECIFIED	
	RELEASES MANUFACTURER OF 5 DOCUMENT CONTAINS CONFIDENTIAL ANI CANNOT BE REPRODUCED OR DIVULGED, WRITTEN AUTHORIZATION FROM TH	O PROPRIETARY N WHOLE OR IN	PART, WI				SHEET SIZE B		DATE 2/1/2021		GLV-40S1 SHEET 4 OF 4	

WEIGHT:





HEIDENHAIN

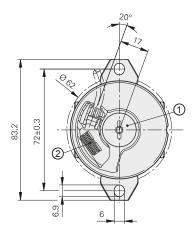
Product Information

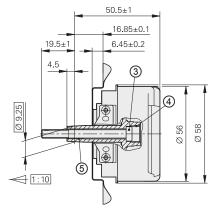
ECN 1313 ECN 1325 ERN 1387

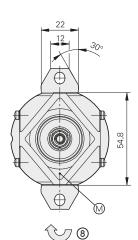
Rotary Encoders with Plane-Surface Coupling for Elevator Servo Drive Control Rotary encoders with integral bearings for elevator technology

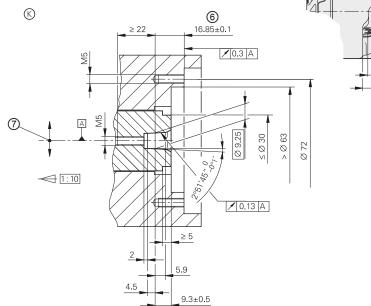
- Simple installation
- Rigid shaft coupling
- Plane-surface coupling for large mounting tolerances
- · Uniform dimensions for various electrical interfaces











- \square = Bearing of mating shaft
- B = Bearing of encoder
- (S) = Required mating dimensions

- 2 = PCB connector
- 3 = Self-tightening screw M5 x 50 DIN 6912 width A/F 4, tightening torque 5+0.5 Nm
- 4 = M10 back-off thread
- 5 = M6 back-off thread
- 6 = Max. permissible tolerance during motor shaft rotation ± 1.5 mm
- 7 = Max. permissible static radial offset of motor shaft in indicated direction ±0.13 mm
- 8 = Direction of shaft rotation for output signals as per the interface description

mm

✐⊕

Tolerancing ISO 8015 ISO 2768 - m H

< 6 mm: ±0.2 mm

	Absolute		Incremental
	ECN 1325	ECN 1313	ERN 1387
Part number	683643-xx	768295-xx	749146-xx
Interface ¹⁾	EnDat 2.2		~ 1 V _{PP}
Ordering designation	EnDat22	EnDat01	-
Position values/revolution	33554432 (25 bits)	8192 (13 bits)	Z1 track ³⁾
Electrically permissible speed/error ²⁾	≤ 15000 rpm (for continuous position value)	≤ 1500 rpm/±1 LSB ≤ 12 000 rpm/±50 LSB	-
Calculation time t _{cal} Clock frequency	≤ 7 μs ≤ 16 MHz	≤ 9 µs ≤ 2 MHz	
Incremental signals ¹⁾	-	~1 V _{PP}	~ 1 V _{PP}
Line count/system accuracy	2048/±20"		
Reference mark	-		One
Cutoff frequency –3 dB	-	≥ 400 kHz	≥ 210 kHz
Electrical connection Via PCB connector	<i>Rotary encoder:</i> 12-pin <i>Temperature sensor</i> ⁴⁾ : 4-pin	12-pin	14-pin
Voltage supply	DC 3.6 V to 14 V		DC 5V ±0.25V
Power consumption ¹⁾ (maximum)	<i>3.6 V</i> : ≤ 600 mW <i>14 V</i> : ≤ 700 mW		-
Current consumption	5 V: 85 mA (typical, without load)		≤ 130 mA (without load)
Stator coupling	Plane-surface coupling		
Shaft	Taper shaft Ø 9.25 mm; taper 1:1	0	
Mech. permiss. speed n	≤ 2000 rpm		
Starting torque	≤ 0.01 Nm (at 20 °C)		
Moment of inertia of rotor	$2.6 \cdot 10^{-6} \text{ kgm}^2$		
Permissible axial motion of measured shaft ⁵⁾	±1.5 mm		
Radial runout of the measured shaft	0.13 mm		
Vibration 55 Hz to 2000 Hz Shock 6 ms	\leq 300 m/s ^{2 6)} (EN 60068-2-6) \leq 2000 m/s ² (EN 60068-2-27)		
Operating temperature	–40 °C to +115 °C		-40 °C to +120 °C
Protection EN 60529	IP40 when mounted		
Mass	≈ 0.25 kg		
1) Soo Interfaces of HEIDENIL			

¹⁾ See Interfaces of HEIDENHAIN Encoders brochure
 ²⁾ Velocity-dependent deviations between the absolute value and incremental signals
 ³⁾ One sine and one cosine signal per revolution
 ⁴⁾ Evaluation optimized for KTY 84-130
 ⁵⁾ Compensation of mounting tolerances and thermal expansion, not dynamic motion
 ⁶⁾ As per standard for room temperature; for operating temperature

Up to +100 °C: \leq 300 m/s² Up to +115 °C or +120 °C: \leq 150 m/s²

Electrical connection

Pin layouts

ECN 1313 pin layout

17-pin con flange so	cket M23							11 • 1 10° 16 12 13 • 2 9° 15 • 14 8• • 17 • • 2 7• • • 5	3	12-pin P	CB conn		
		Power	supply			I	ncrement	al signals ¹	1)		Serial dat	ta transfer	
	7	1	10	4	11	15	16	12	13	14	17	8	9
E 12	1b	6a	4b	3a	/	2a	5b	4a	3b	6b	1a	2b	5a
	U _P	Sensor U _P	0V •	Sensor 0 ∨	Internal shield	A+	A –	B+	В-	DATA	DATA	CLOCK	CLOCK
	Brown/ Green	Blue	White/ Green	White	/	Green/ Black	Yellow/ Black	Blue/ Black	Red/ Black	Gray	Pink	Violet	Yellow

	Other	signals
	5	6
	/	/
E 12	/	/
	Brown ²⁾	White ²⁾

Cable shield connected to housing; U_P = Power supply voltage; T = Temperature Sensor: The sensor line is connected in the encoder with the corresponding power line. Vacant pins or wires must not be used.

	/	/	1) 2)
E 12	/	/	
	Brown ²⁾	White ²⁾	

Only with ordering designations EnDat 01 and EnDat 02 Only for cables inside the motor housing

ECN 1325 pin lavout

8-pin cou flange so					6 5 4 7 3 1 2 2		9-pin flang M23	_		7 • 2 9 • 2 6 • 3 5 • 4
16-pin PCB conn	ector	b a	L L L L L L L L L L L L L L L L L L L		• 16					
		Voltage	supply			Serial da	ta transfer		Other	signals
— M12	8	2	5	1	3	4	7	6	/	/
— M23	3	7	4	8	5	6	1	2	/	1
E 16	1b	6a	4b	3a	6b	1a	2b	5a	8a	8b
-	U _P	Sensor UP	0 V •	Sensor 0 ∨	DATA	DATA	CLOCK	CLOCK	T+	T-
€	Brown/ Green	Blue	White/ Green	White	Gray	Pink	Violet	Yellow	Brown	Green

Cable shield connected to housing

U_P = Power supply; **T** = Temperature

Sensor: The sensor line is connected in the encoder with the corresponding power line. Vacant pins or wires must not be used.

ERN 1387 pin layout

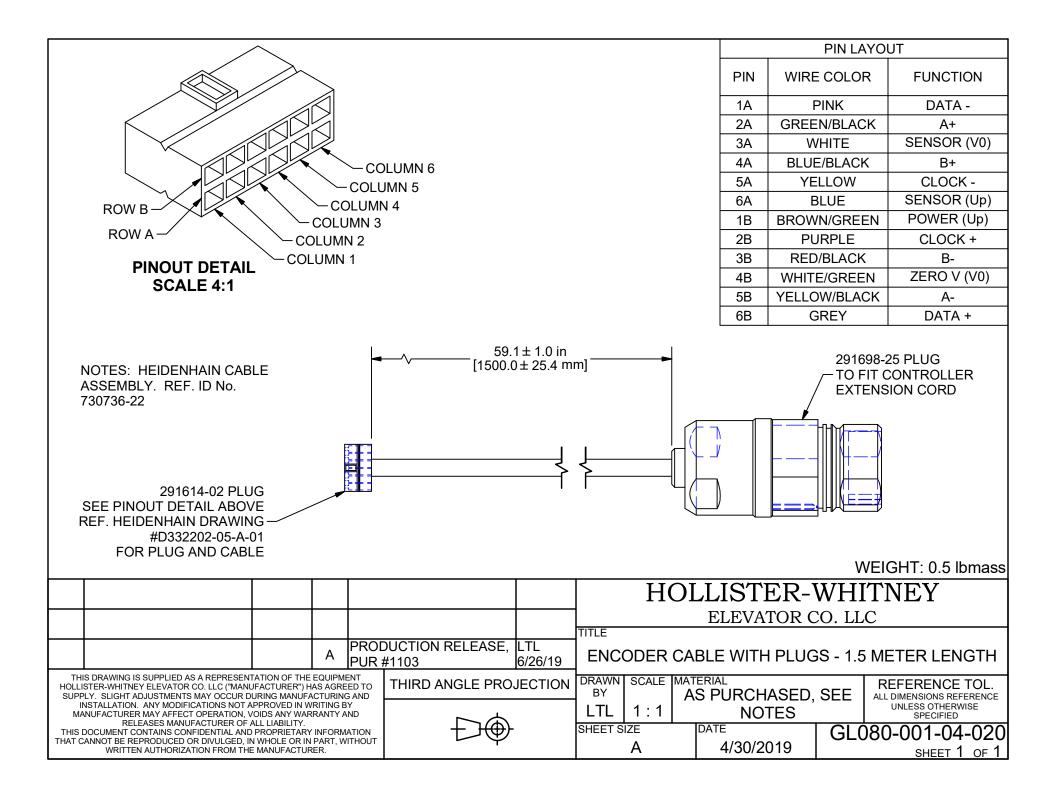
17-pin coupling or flange socket M23							$\begin{array}{c} 11 \bullet 1 \\ 10^{\circ} 16 \\ 9^{\circ} \\ 15 \bullet 14 \\ 8 \bullet \\ 6 \\ 7^{\circ} \\ 6 \\ 6 \\ \end{array}$		14-pin PCB connector		
	Voltage supply					Incremental signals					
	7	1	10	4	11	15	16	12	13	3	2
Ε	1b	7a	5b	3a	/	6b	2a	3b	5a	4b	4a
	U _P	Sensor U _P	0V •	Sensor 0 ∨	Internal shield	A+	A –	B+	В-	R+	R-
	Brown/ Green	Blue	White/ Green	White	/	Green/ Black	Yellow/ Black	Blue/Black	Red/Black	Red	Black

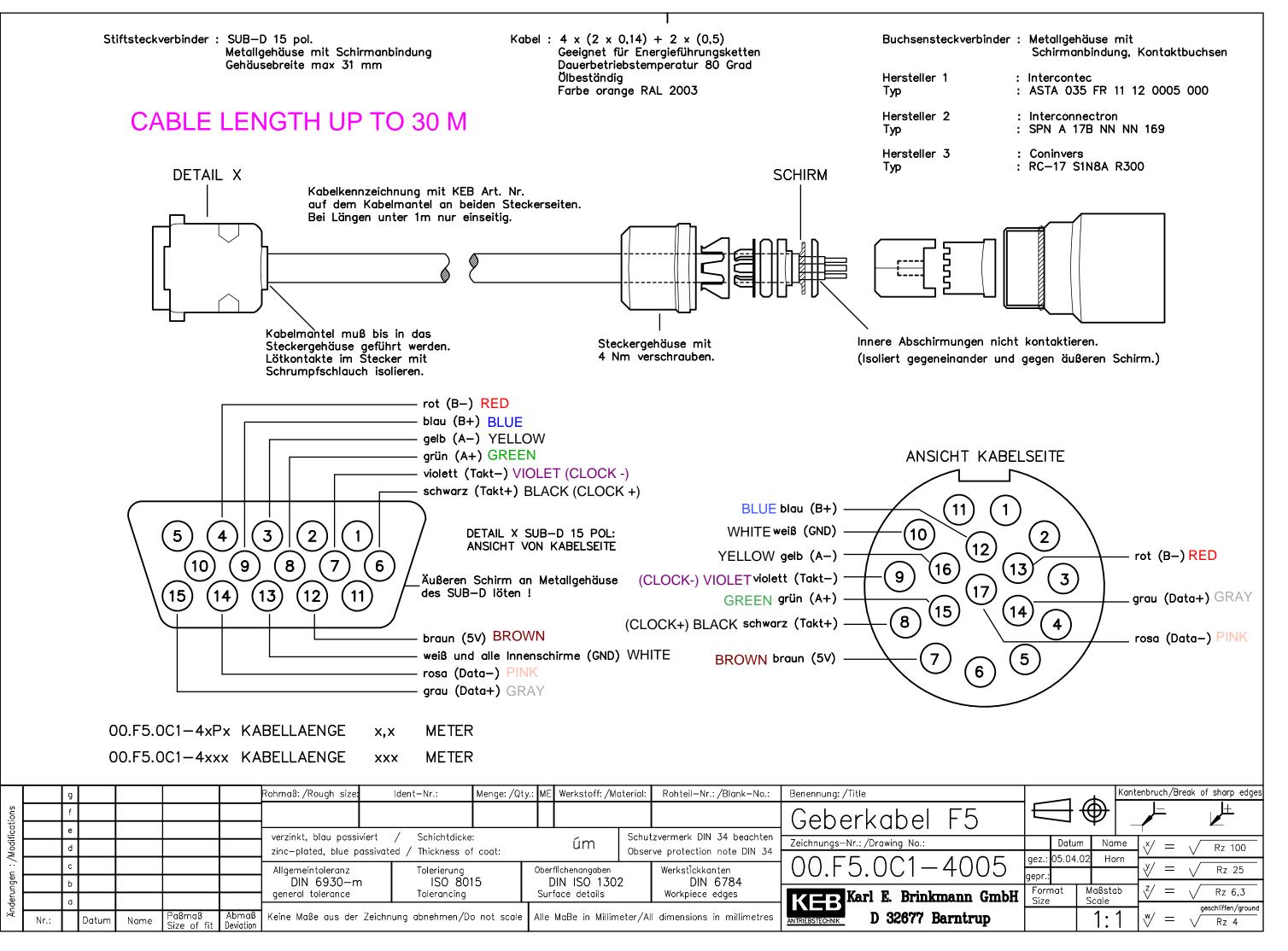
	Other signals						
	14	17	9	8	5	6	
E	7b	1a	2b	6a	/	/	
	C+	C–	D+	D-	T+ ¹⁾	T – ¹⁾	
	Gray	Pink	Yellow	Violet	Green	Brown	

Cable shield connected to housing;

 U_P = Power supply; **T** = Temperature Sensor: The sensor line is connected internally with the corresponding power line. Vacant pins or wires must not be used.

¹⁾ Only for cables inside the motor housing





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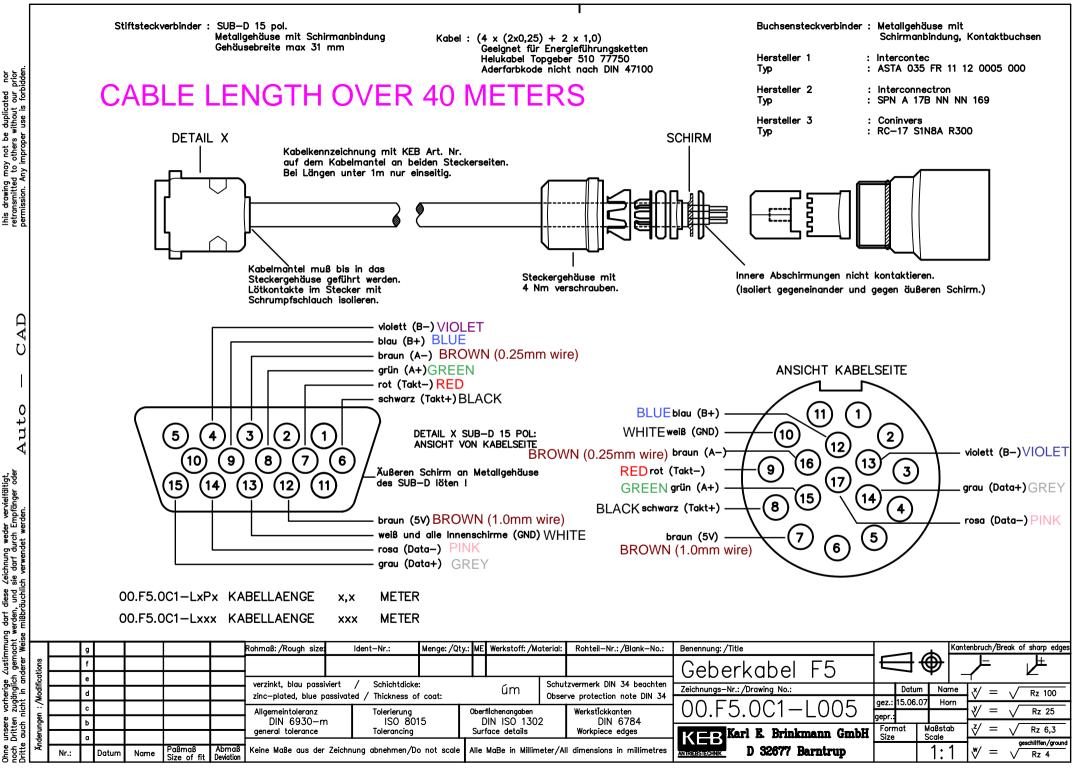
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GERMAN	ENGLISH
ROT	RED
BLAU	BLUE
GELB	YELLOW
GRÜN	GREEN
VIOLETT	VIOLET
SCHWARZ	BLACK
BRAUN	BROWN
WEIβ	WHITE
ROSA	PINK
GRAU	GREY